Register allocation

Advanced Compiler Construction
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Register allocation

Register allocation consists in:

- rewriting a program that makes use of an unbounded number of virtual or pseudo-registers,
- into one that only uses physical (machine) registers.

Some virtual registers might have to be **spilled** to memory.

Register allocation is done:

- very late in the compilation process – typically only instruction scheduling comes later,
- on an IR very close to machine code.

Setting the scene

We will do register allocation on an RTL with:

- n machine registers R_0, …, R_{n-1} (some with non-numerical indexes like the link register R_{LK}),
- unbounded number of virtual registers v_0, v_1, …

Of course, virtual registers are only available before register allocation.

Running example

Euclid's algorithm to compute greatest common divisor.

In L_3

```
(defrec gcd
  (fun (a b)
    (if (= 0 b)
        a
        (gcd b (% a b)))))
```

In RTL

```
gcd:  R3 ← done
      if R2 = 0 goto R3
      R3 ← R2
      R2 ← R1 % R2
      R1 ← R3
      R3 ← gcd
      goto R3
done: goto RLK
```

Calling conventions:

- the arguments are passed in R_1, R_2, …
- the return address is passed in R_{LK},
- the return value is passed in R_1.

Register allocation example

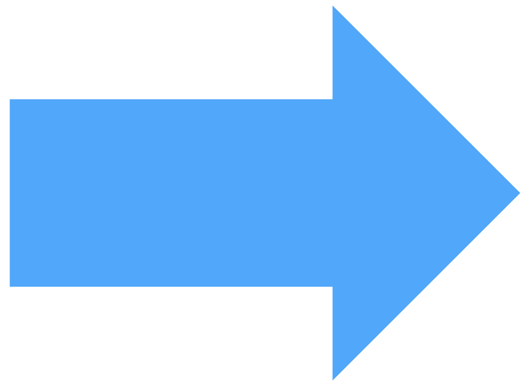
Before register allocation

```
gcd:   v0 ← RLK
       v1 ← R1
       v2 ← R2
loop:  v3 ← done
       if v2 = 0 goto v3
       v4 ← v2
       v2 ← v1 % v2
       v1 ← v4
       v5 ← loop
       goto v5
done:  R1 ← v1
       goto v0
```

R_1, R_2: parameters

R_{LK}: return address

allocable registers: R_1, R_2, R_3, R_{LK}



After register allocation

```
gcd:
loop:  R3 ← done
       if R2 = 0 goto R3
       R3 ← R2
       R2 ← R1 % R2
       R1 ← R3
       R3 ← loop
       goto R3
done:  goto RLK
```

Allocation:

$v_0 \rightarrow R_{LK}$

$v_1 \rightarrow R_1$

$v_2 \rightarrow R_2$

$v_3, v_4, v_5 \rightarrow R_3$

Techniques

We will study two commonly used techniques:

1. register allocation by **graph coloring**, which:
   - produces good results,
   - is relatively slow,
   - is therefore used mostly in batch compilers,
2. **linear scan** register allocation, which:
   - produces average results,
   - is very fast,
   - is therefore used mostly in JIT compilers.

Both are **global**: they allocate registers for a whole function at a time.

Technique #1: graph coloring

Allocation by graph coloring

Register allocation can be reduced to graph coloring:

1. build the **interference graph**, which has:
   - one node per register – real or virtual,
   - one edge between each pair of nodes whose registers are live at the same time.
2. color the interference graph with at most K colors (K = number of available registers), so that all nodes have a different color than all their neighbors.

Problems:

- coloring is NP-complete for arbitrary graphs,
- a K-coloring might not even exist.

Interference graph example

Program

```
gcd:
   v0 ← RLK
   v1 ← R1
   v2 ← R2
loop:
   v3 ← done
   if v2=0 goto v3
   v4 ← v2
   v2 ← v1 % v2
   v1 ← v4
   v5 ← loop
   goto v5
done:
   R1 ← v1
   goto v0
```

Liveness

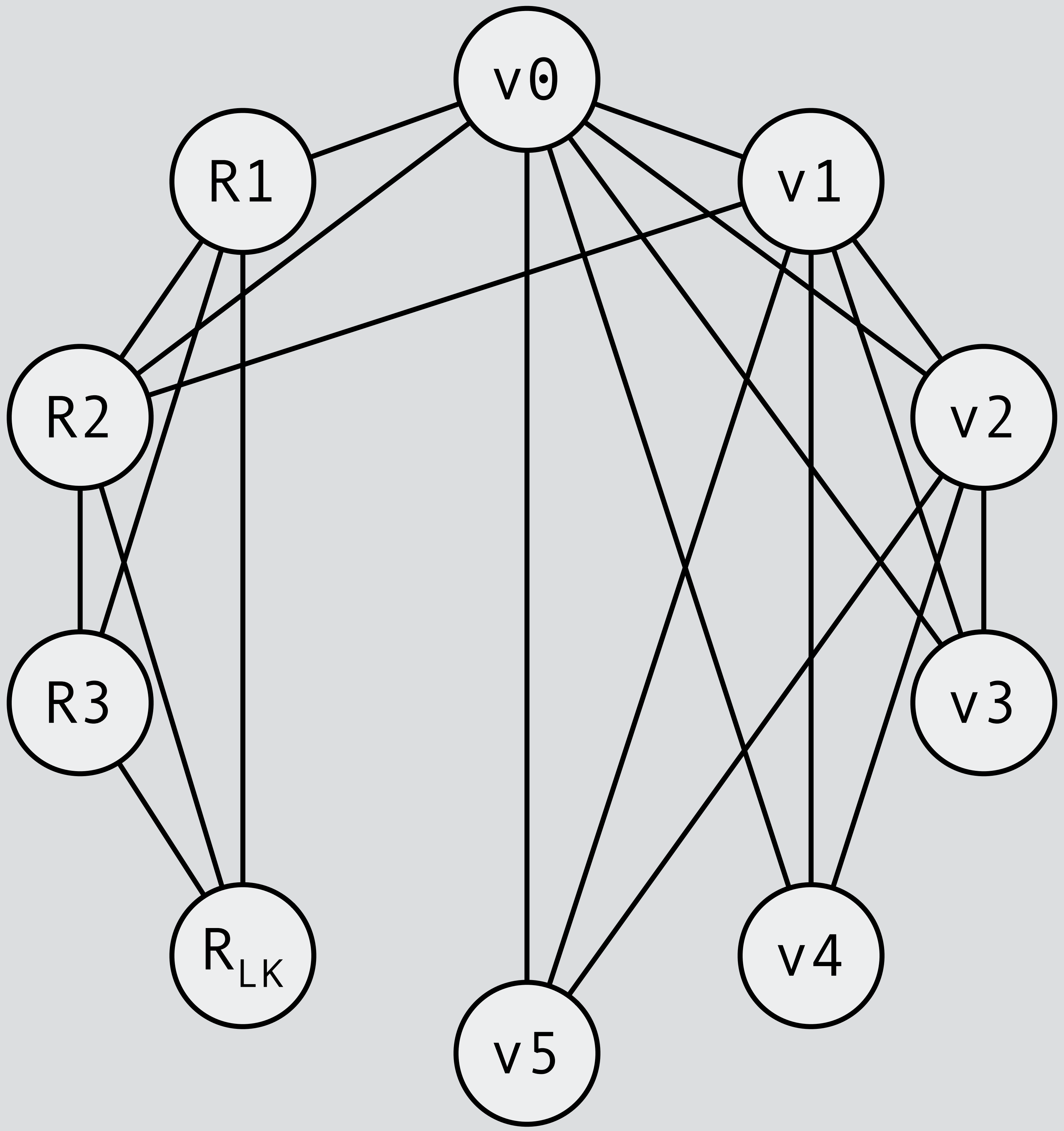
{in}{out}

$\{R_1,R_2,R_{LK}\}\{R_1,R_2,v_0\}$
$\{R_1,R_2,v_0\}\{R_2,v_0,v_1\}$
$\{R_2,v_0,v_1\}\{v_0\text{-}v_2\}$

$\{v_0\text{-}v_2\}\{v_0\text{-}v_3\}$
$\{v_0\text{-}v_3\}\{v_0\text{-}v_2\}$
$\{v_0\text{-}v_2\}\{v_0\text{-}v_2,v_4\}$
$\{v_0\text{-}v_2,v_4\}\{v_0\text{-}v_2,v_4\}$
$\{v_0\text{-}v_2,v_4\}\{v_0\text{-}v_2\}$
$\{v_0\text{-}v_2\}\{v_0\text{-}v_2,v_5\}$
$\{v_0\text{-}v_2,v_5\}\{v_0\text{-}v_2\}$

$\{v_0,v_1\}\{R_1,v_0\}$
$\{R_1,v_0\}\{R_1\}$

Interference graph

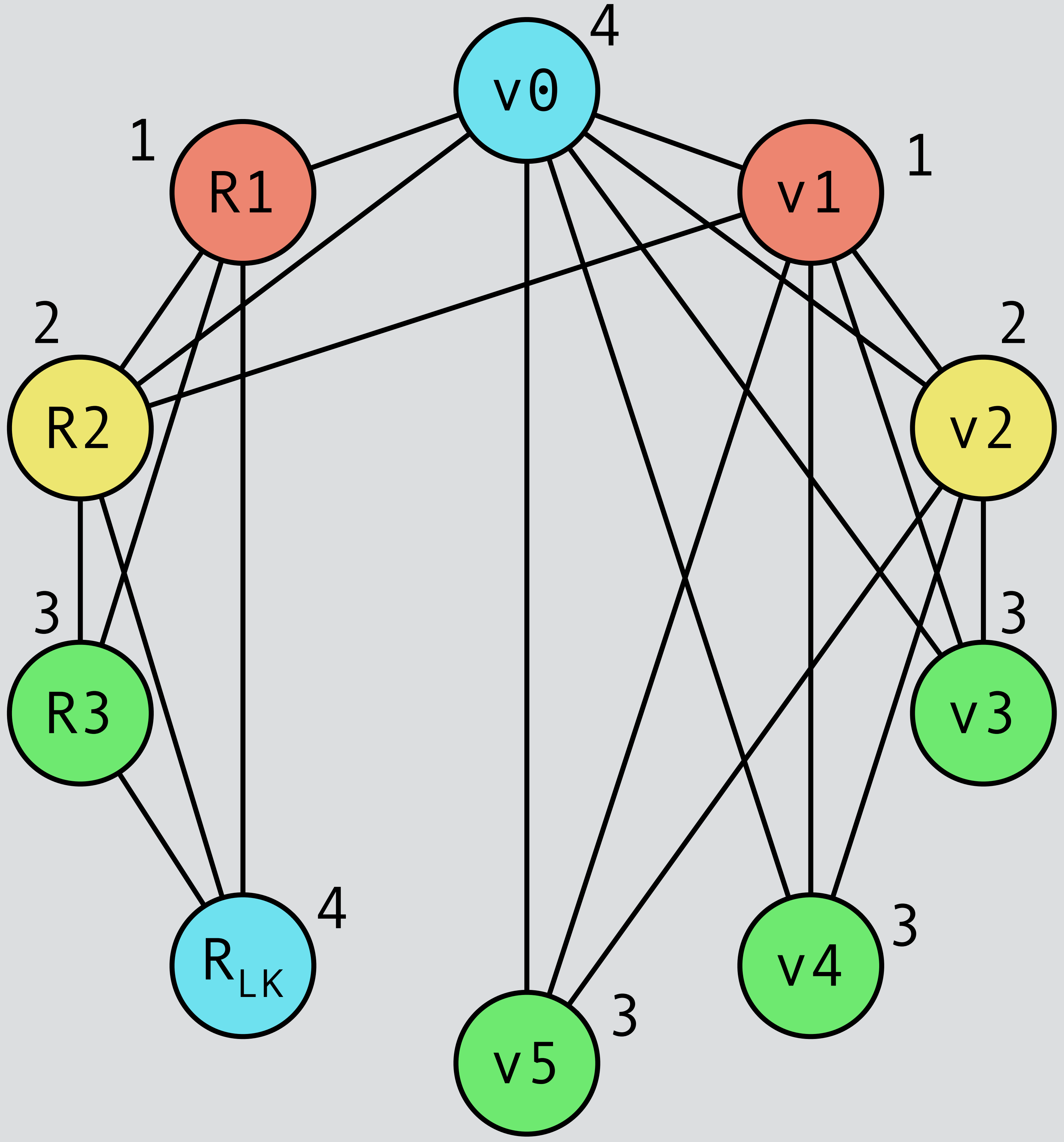


Coloring example

Original prog.

```
gcd:
  v₀ ← R_LK
  v₁ ← R₁
  v₂ ← R₂
loop:
  v₃ ← done
  if v₂=0 goto v₃
  v₄ ← v₂
  v₂ ← v₁ % v₂
  v₁ ← v₄
  v₅ ← loop
  goto v₅
done:
  R₁ ← v₁
  goto v₀
```

Colored interference graph



Rewritten prog.

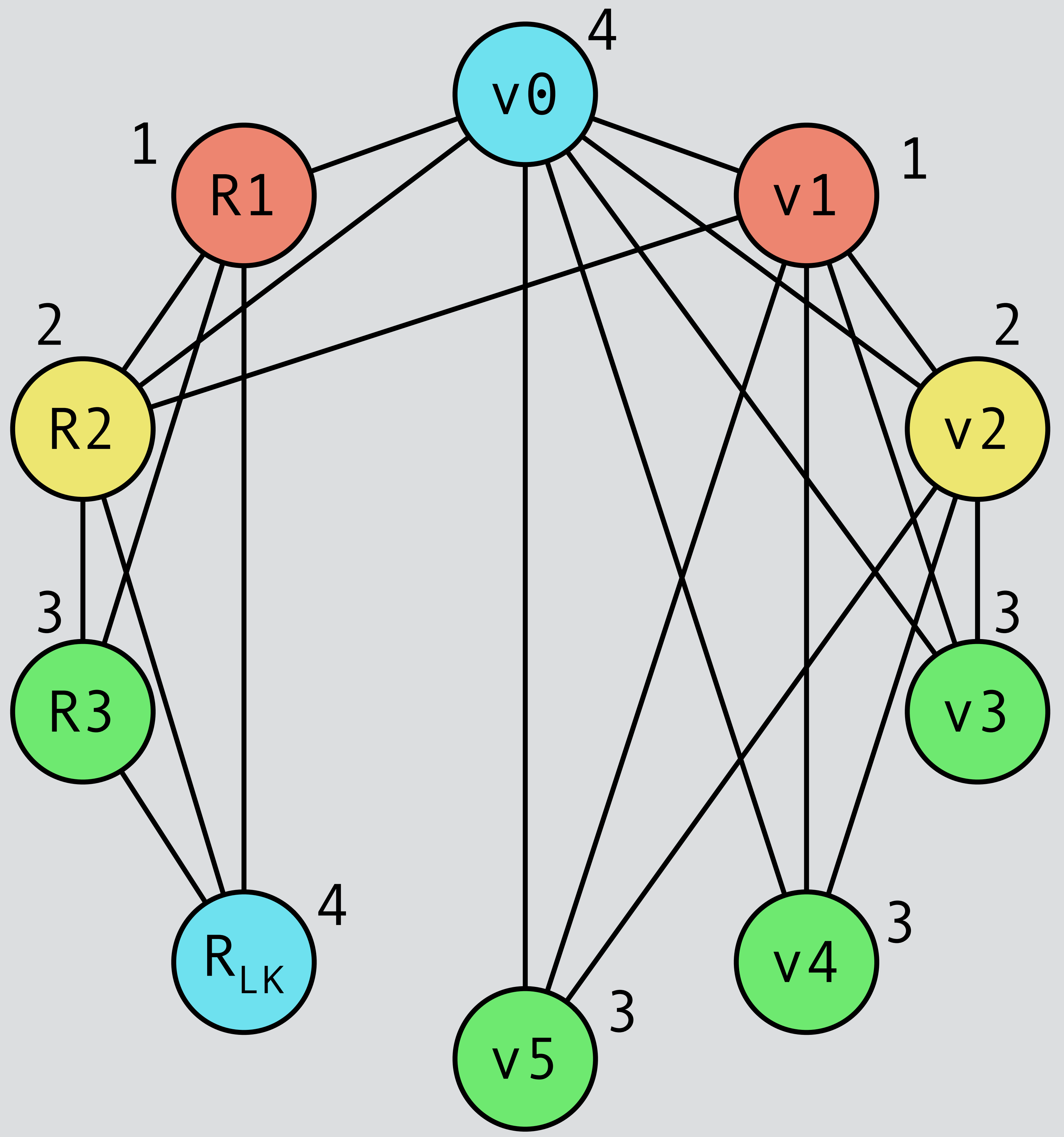
```
gcd:
  R_LK ← R_LK
  R₁ ← R₁
  R₂ ← R₂
loop:
  R₃ ← done
  if R₂=0 goto R₃
  R₃ ← R₂
  R₂ ← R₁ % R₂
  R₁ ← R₃
  R₃ ← loop
  goto R₃
done:
  R₁ ← R₁
  goto R_LK
```

Coloring example

Original prog.

gcd:
  v_0 ← R_{LK}
  v_1 ← R_1
  v_2 ← R_2
loop:
  v_3 ← done
  if v_2=0 goto v_3
  v_4 ← v_2
  v_2 ← v_1 % v_2
  v_1 ← v_4
  v_5 ← loop
  goto v_5
done:
  R_1 ← v_1
  goto v_0

Colored interference graph



Rewritten prog.

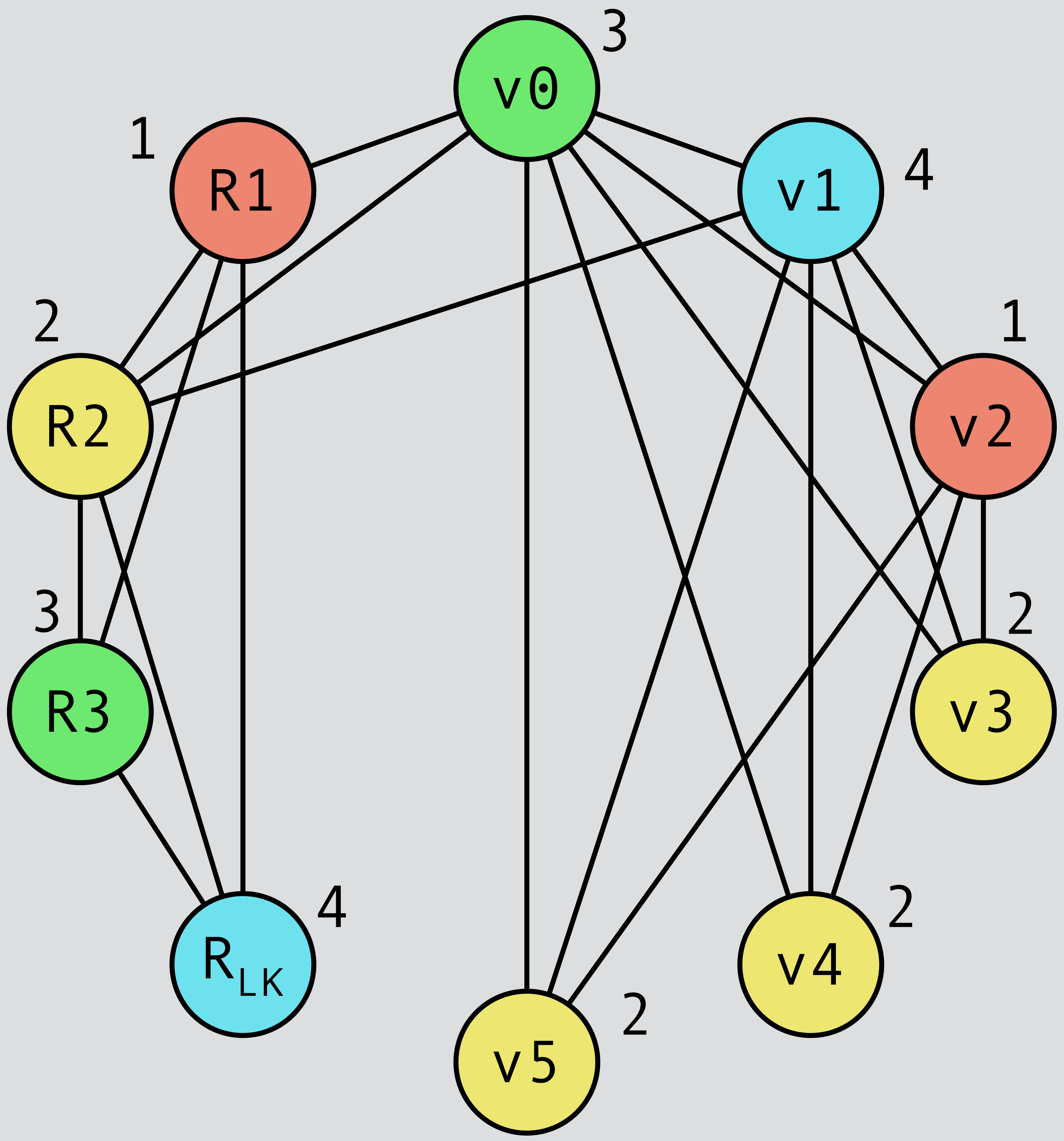
gcd:
  ~~R_{LK} ← R_{LK}~~
  ~~R_1 ← R_1~~
  ~~R_2 ← R_2~~
loop:
  R_3 ← done
  if R_2=0 goto R_3
  R_3 ← R_2
  R_2 ← R_1 % R_2
  R_1 ← R_3
  R_3 ← loop
  goto R_3
done:
  ~~R_1 ← R_1~~
  goto R_{LK}

Coloring example (2)

Original prog.

```
gcd:
  v0 ← RLK
  v1 ← R1
  v2 ← R2
loop:
  v3 ← done
  if v2=0 goto v3
  v4 ← v2
  v2 ← v1 % v2
  v1 ← v4
  v5 ← loop
  goto v5
done:
  R1 ← v1
  goto v0
```

Colored interference graph



Rewritten prog.

```
gcd:
  R3 ← RLK
  RLK ← R1
  R1 ← R2
loop:
  R2 ← done
  if R1=0 goto R2
  R2 ← R1
  R1 ← RLK % R1
  RLK ← R2
  R2 ← loop
  goto R2
done:
  R1 ← RLK
  goto R3
```

This second coloring is also correct, but produces worse code!

Coloring by simplification

Coloring by simplification is a heuristic technique to color a graph with K colors:

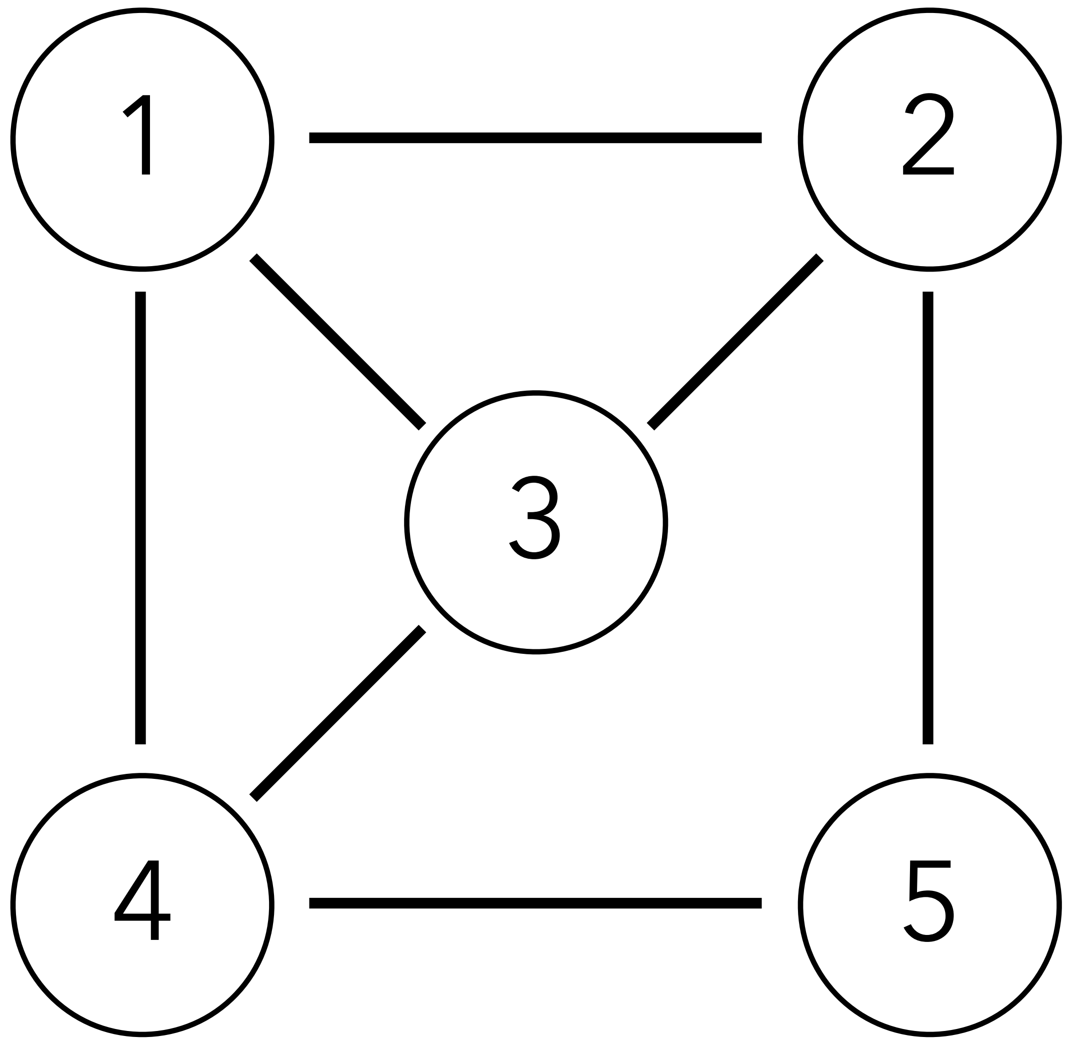
1. find a node n with less than K neighbors,
2. remove it from the graph,
3. recursively color the simplified graph,
4. color n with any color not used by its neighbors.

What if there is no node with less than K neighbors?

- a K-coloring might not exist,
- but simplification is attempted nevertheless.

Coloring by simplification

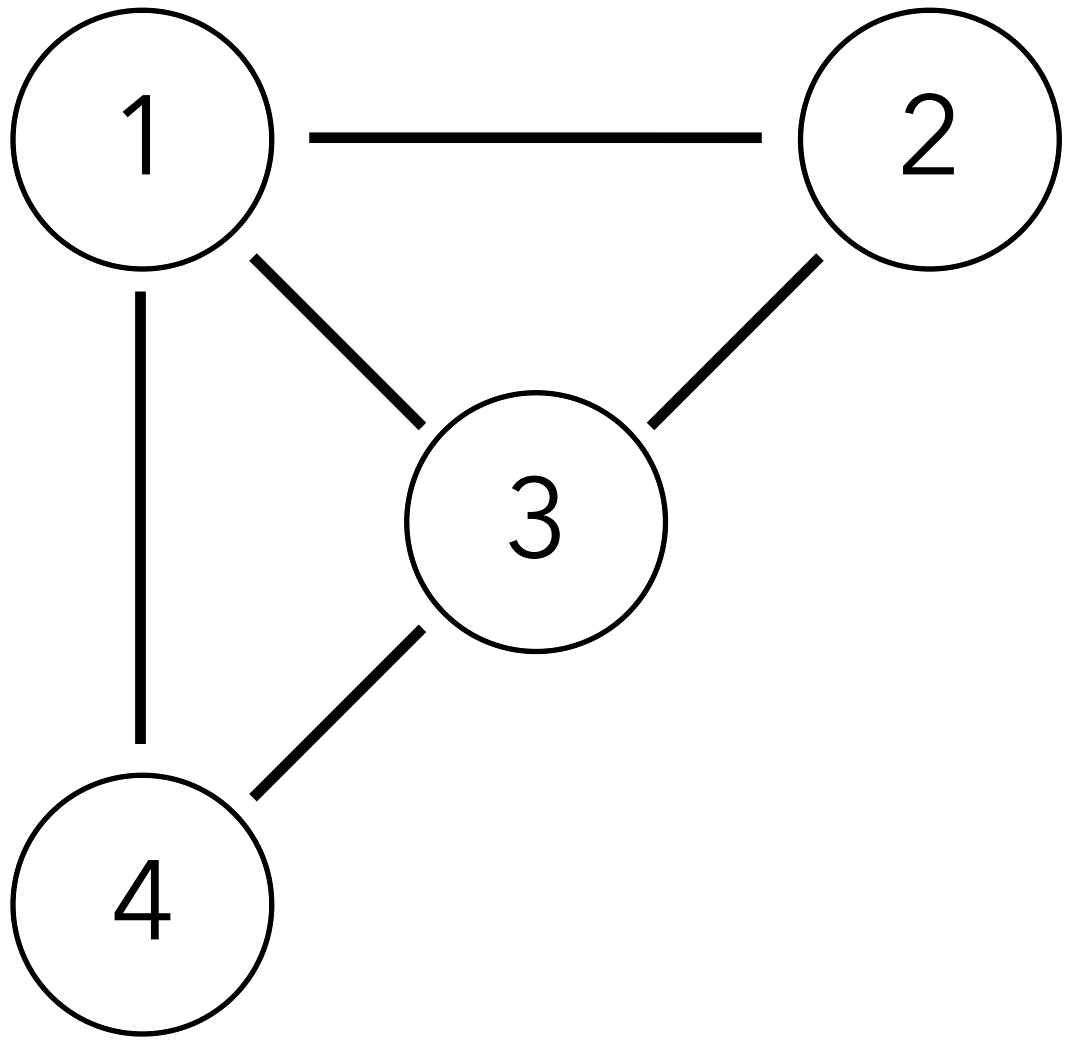
Number of available colors (K): 3



Stack of removed nodes:

Coloring by simplification

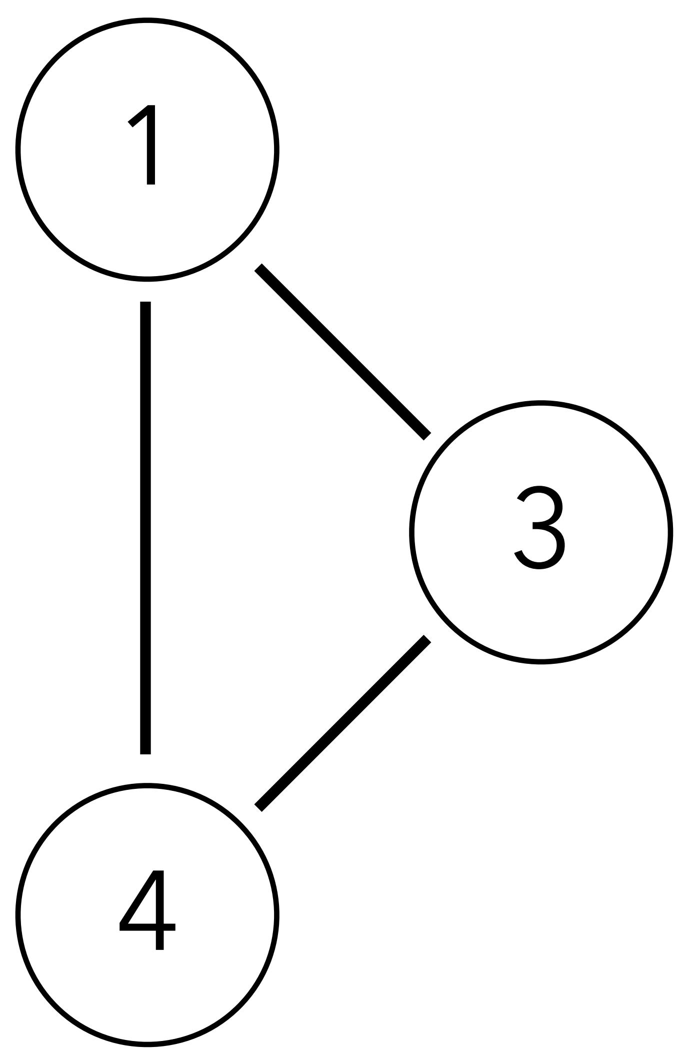
Number of available colors (K): 3



Stack of removed nodes: 5

Coloring by simplification

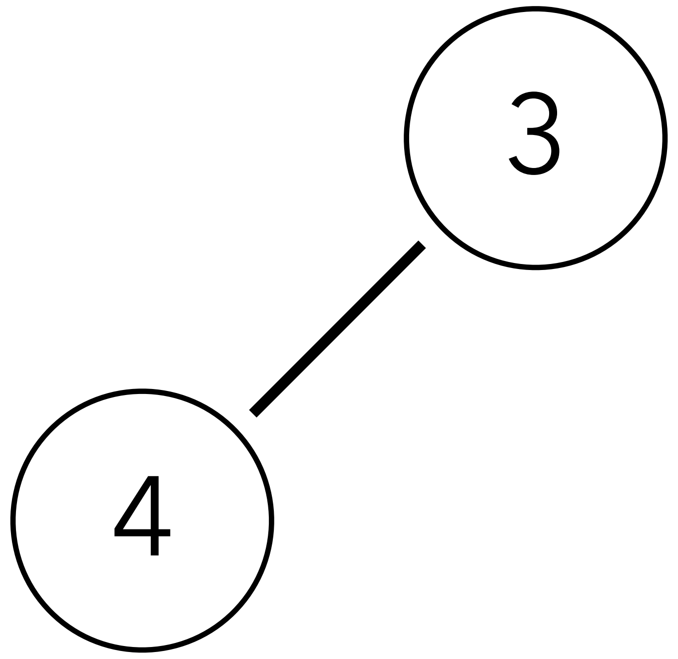
Number of available colors (K): 3



Stack of removed nodes: 5 2

Coloring by simplification

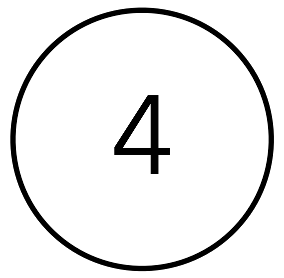
Number of available colors (K): 3



Stack of removed nodes: 5 2 1

Coloring by simplification

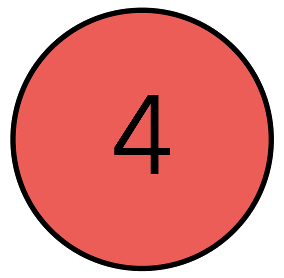
Number of available colors (K): 3



Stack of removed nodes: 5 2 1 3

Coloring by simplification

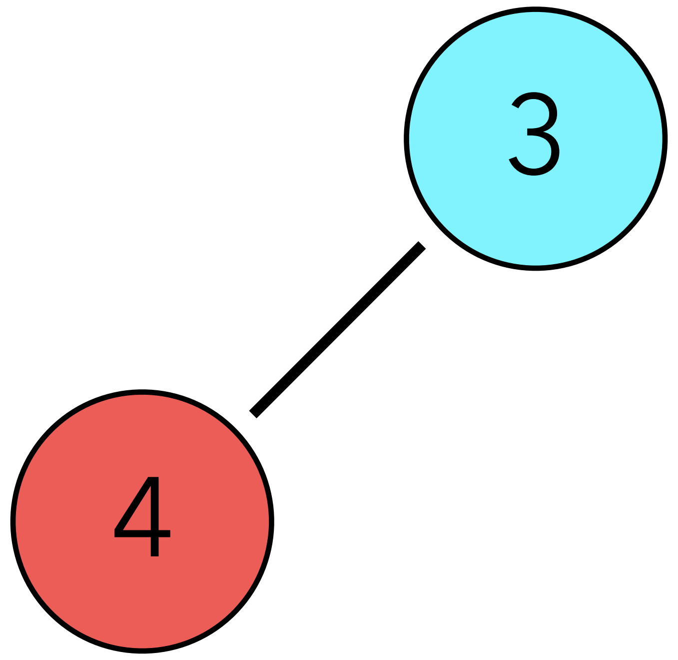
Number of available colors (K): 3



Stack of removed nodes: 5 2 1 3

Coloring by simplification

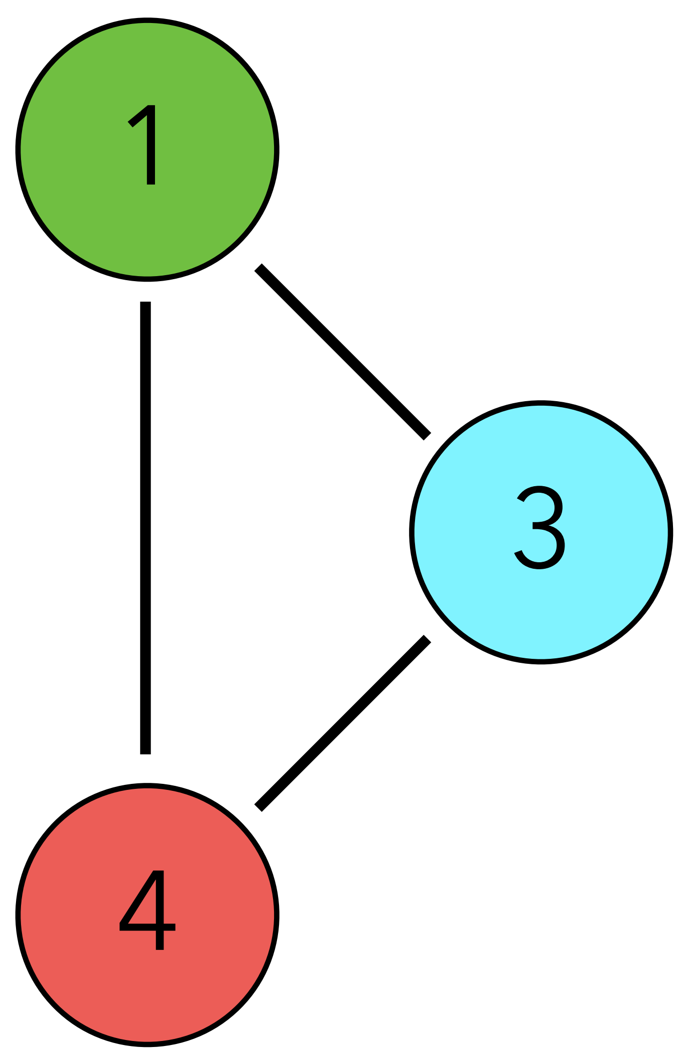
Number of available colors (K): 3



Stack of removed nodes: 5 2 1

Coloring by simplification

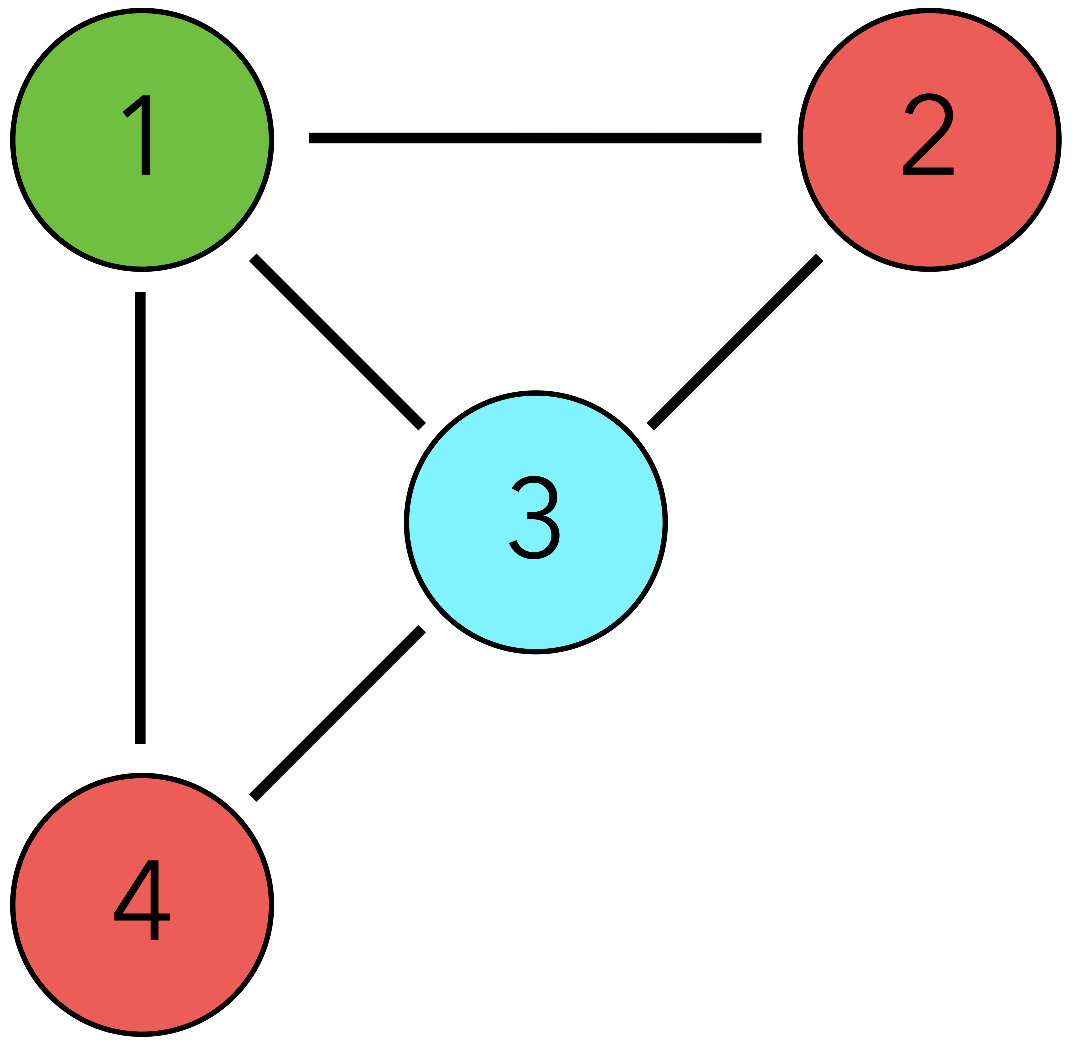
Number of available colors (K): 3



Stack of removed nodes: 5 2

Coloring by simplification

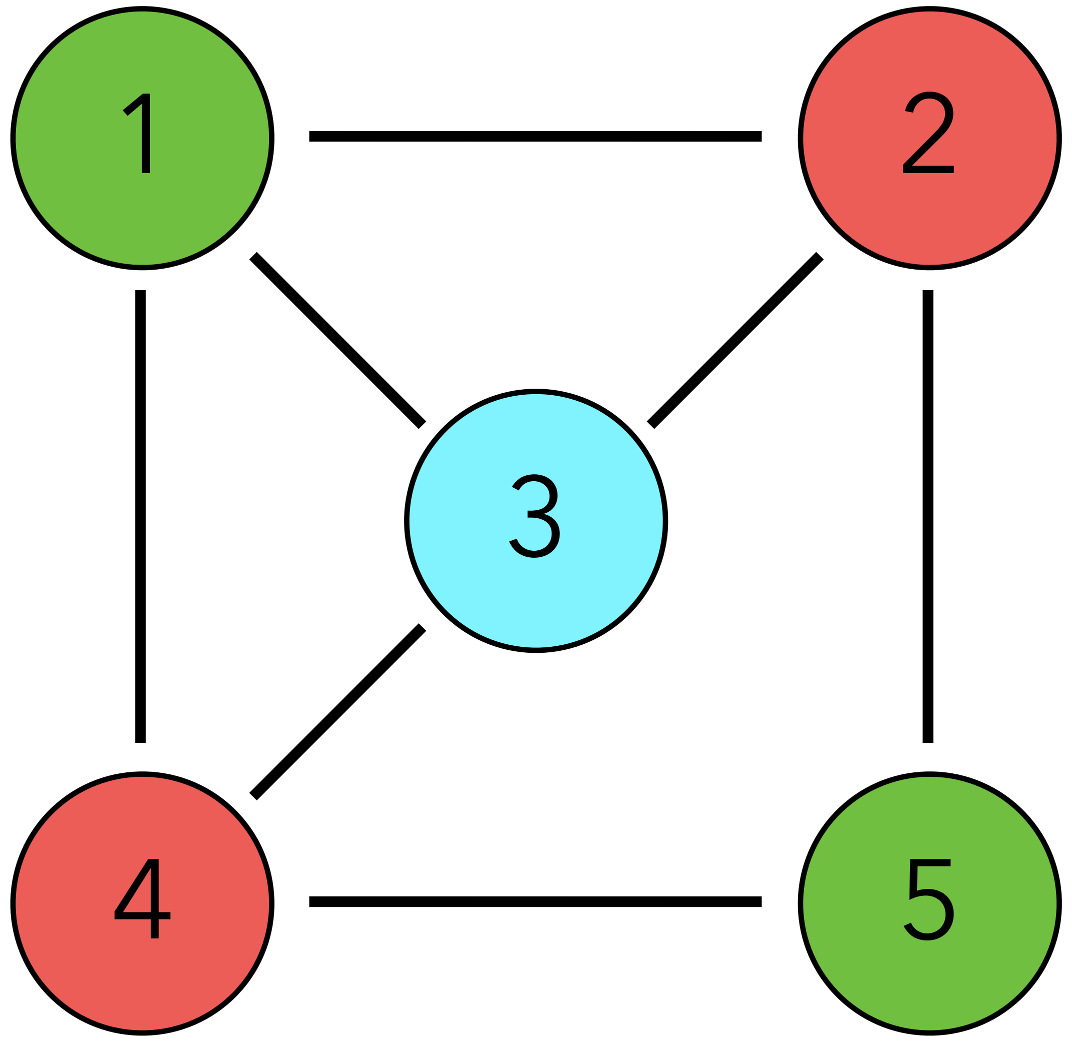
Number of available colors (K): 3



Stack of removed nodes: 5

Coloring by simplification

Number of available colors (K): 3



Stack of removed nodes:

Spilling

(Optimistic) spilling

What if all nodes have K or more neighbors during simplification?

A node n must be chosen to be **spilled** and its value stored in memory instead of in a register:

- remove its node from the graph (assuming no interference between spilled value and other values),
- recursively color the simplified graph as usual.

Once recursive coloring is done, two cases:

1. by chance, the neighbors of n do not use all the possible colors, n is not spilled,
2. otherwise, n is really spilled.

Spill costs

Which node should be spilled? Ideally one:

- whose value is not frequently used, and/or
- that interferes with many other nodes.

For that, compute the spill cost of a node n as:

$$cost(n) = (rw_0(n) + 10\ rw_1(n) + \ldots + 10^k\ rw_k(n)) / degree(n)$$

where:

- $rw_i(n)$ is the number of times the value of n is read or written in a loop of depth i,
- degree(n) is the number of edges adjacent to n in the interference graph.

Then spill the node with lowest cost.

Spilling of pre-colored nodes

The interference graph contains nodes corresponding to the physical registers of the machine:

- they are said to be **pre-colored**, as their color is given by the machine register they represent,
- they should never be simplified, as they cannot be spilled (they are physical registers!).

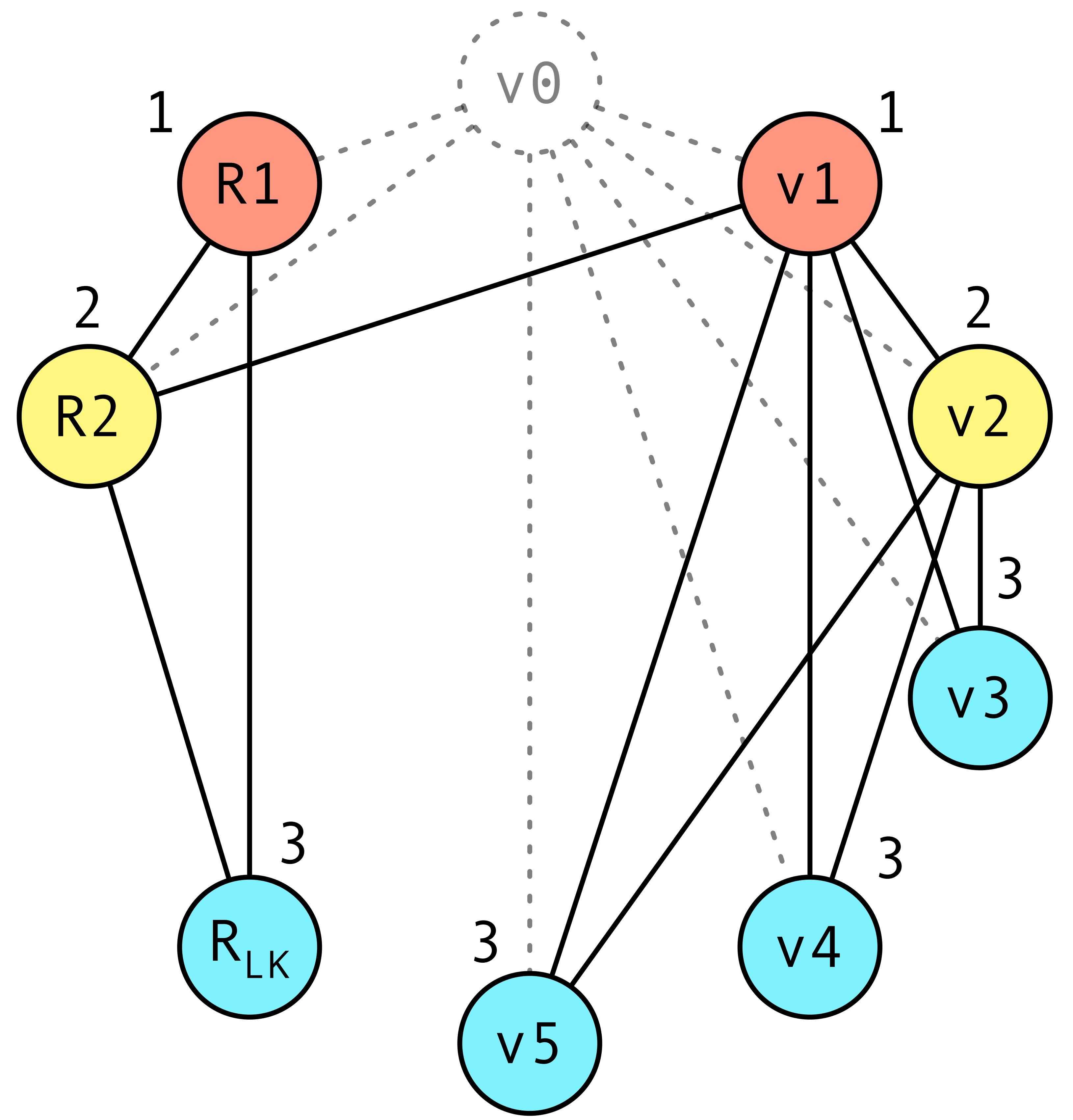
Spilling example: costs

```
gcd:
   v₀ ← R_LK
   v₁ ← R₁
   v₂ ← R₂
loop:
   v₃ ← done
   if v₂=0 goto v₃
   v₄ ← v₂
   v₂ ← v₁ % v₂
   v₁ ← v₄
   v₅ ← loop
   goto v₅
done:
   R₁ ← v₁
   goto v₀
```

node	rw_0	rw_1	deg.	cost
v_0	2	0	7	0.29
v_1	2	2	6	3.67
v_2	1	4	6	6.83
v_3	0	2	3	6.67
v_4	0	2	3	6.67
v_5	0	2	3	6.67

$$\text{cost} = (rw_0 + 10\ rw_1) / \text{degree}$$

Spilling example



Consequences of spilling

After spilling, rewrite the program to:

- insert code just before the spilled value is read, to fetch it from memory,
- insert code just after the spilled value is written, to write it back to memory.

But: spilling code introduces new virtual registers, so register allocation must be redone!

In practice, 1–2 iterations are enough in almost all cases.

Spilling code integration

Original program

```
gcd:
   v0 ← RLK
   v1 ← R1
   v2 ← R2
loop:
   v3 ← done
   if v2 = 0 goto v3
   v4 ← v2
   v2 ← v1 % v2
   v1 ← v4
   v5 ← loop
   goto v5
done:
   R1 ← v1
   goto v0
```

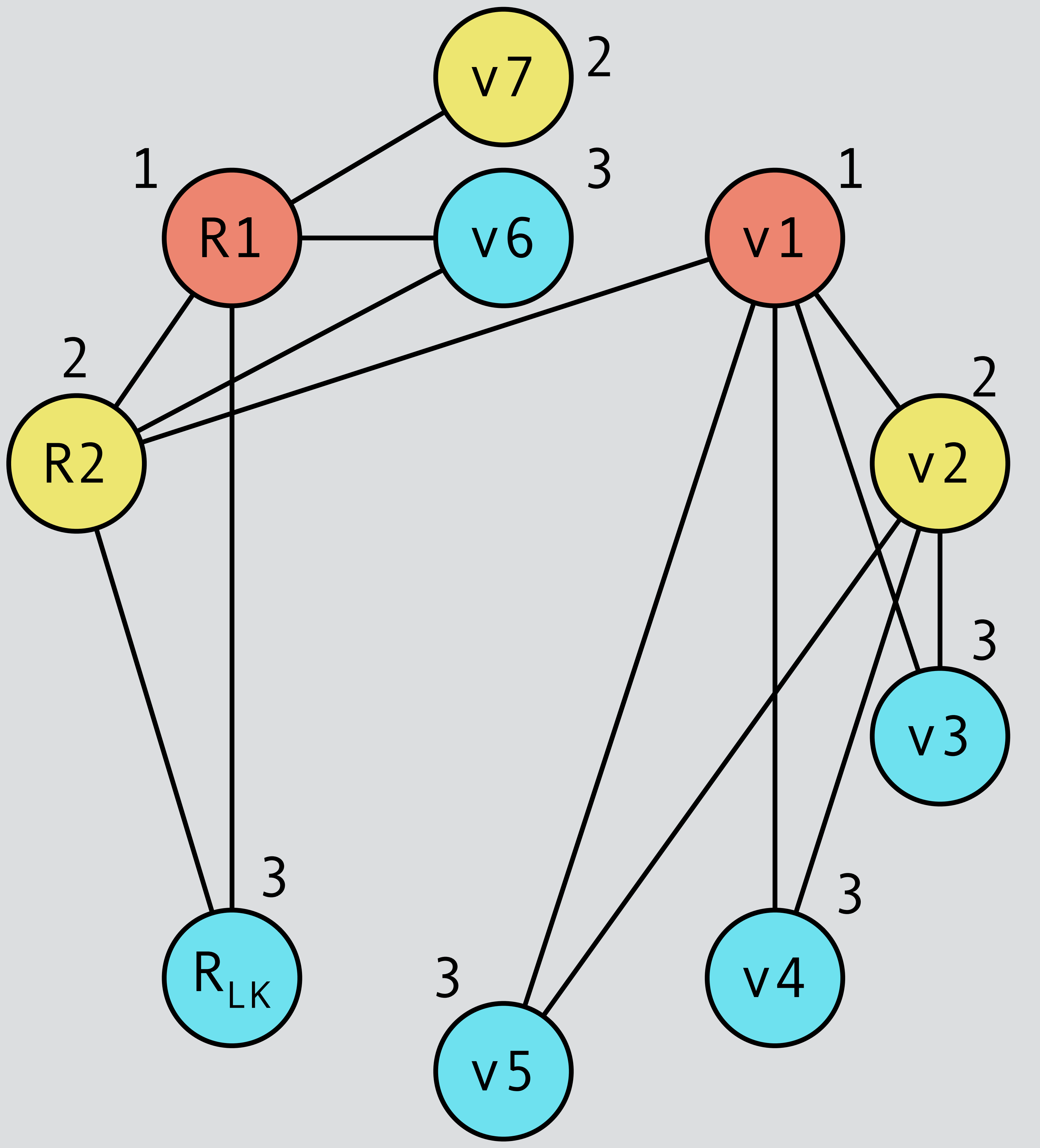
spilling of v_0

Rewritten program

```
gcd:
   v6 ← RLK
   push v6
   v1 ← R1
   v2 ← R2
loop:
   v3 ← done
   if v2 = 0 goto v3
   v4 ← v2
   v2 ← v1 % v2
   v1 ← v4
   v5 ← loop
   goto v5
done:
   R1 ← v1
   pop v7
   goto v7
```

New interference graph

Interference graph w/ spilling

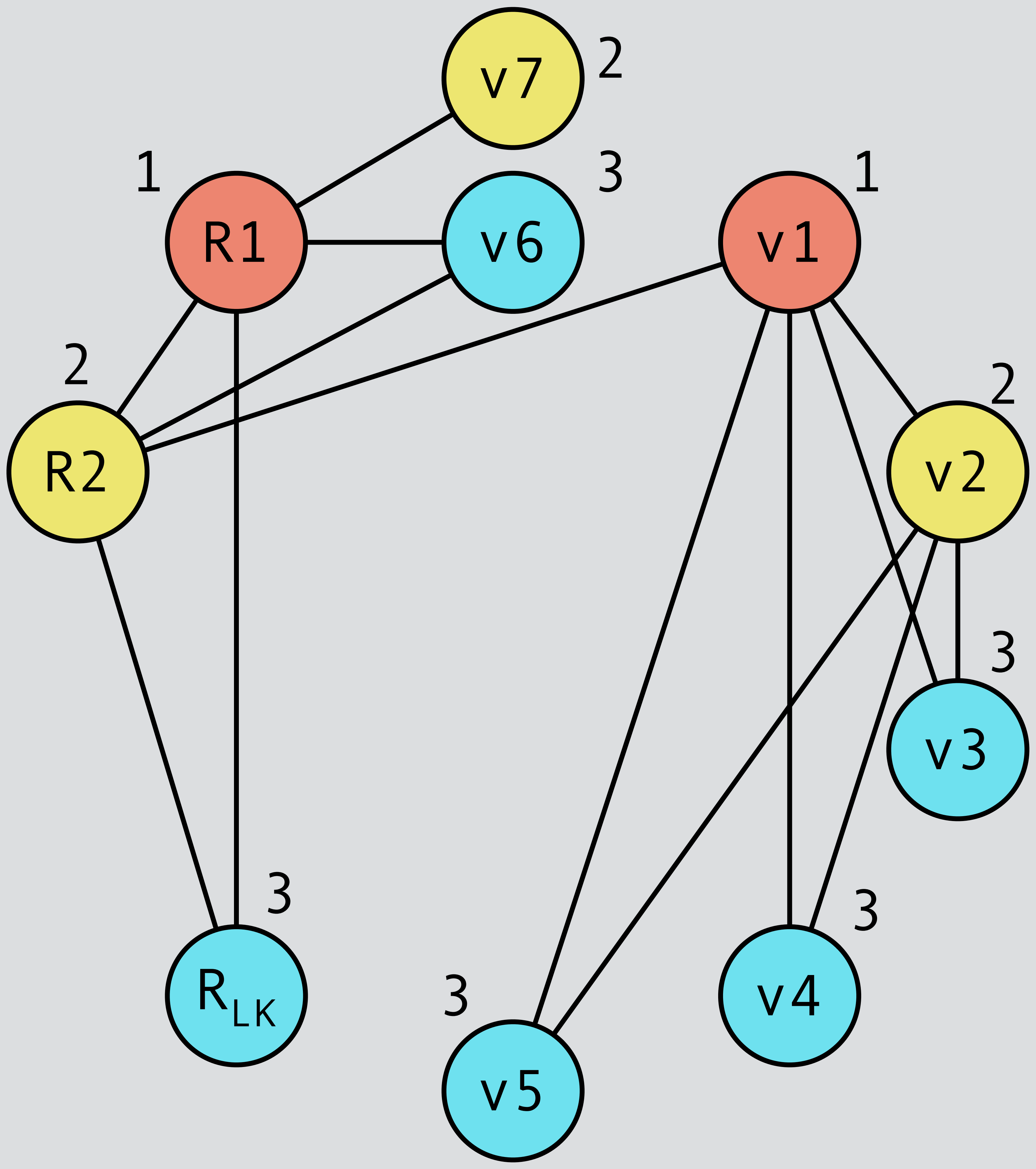


Final program

```
gcd:
   R_LK ← R_LK
   push R_LK
   R1 ← R1
   R2 ← R2
loop:
   R_LK ← done
   if R2 = 0 goto R_LK
   R_LK ← R2
   R2 ← R1 % R2
   R1 ← R_LK
   R_LK ← loop
   goto R_LK
done:
   R1 ← R1
   pop R2
   goto R2
```

New interference graph

Interference graph w/ spilling



Final program

```
gcd:
  ~~RLK ← RLK~~
  push RLK
  ~~R1 ← R1~~
  ~~R2 ← R2~~
loop:
  RLK ← done
  if R2 = 0 goto RLK
  RLK ← R2
  R2 ← R1 % R2
  R1 ← RLK
  RLK ← loop
  goto RLK
done:
  ~~R1 ← R1~~
  pop R2
  goto R2
```

Coalescing

Coloring quality

Two valid K-colorings of an interference graph are not necessarily equivalent: one can lead to a much shorter program than the other.

Why? Because "move" instruction of the form

$v_1 \leftarrow v_2$

can be removed if v_1 and v_2 end up being allocated to the same register (also holds when v_1 or v_2 is a real register).

Goal: make this happen as often as possible.

Coalescing

If v_1 and v_2 do not interfere, a move instruction of the form

$v_1 \leftarrow v_2$

can always be removed by replacing v_1 and v_2 by a new virtual register $v_{1\&2}$.

This is called **coalescing**, as the nodes of v_1 and v_2 in the interference graph coalesce into a single node.

Coalescing issue

Coalescing is not always a good idea!

Might turn a graph that is K-colorable into one that isn't, which implies spilling.

Therefore: use conservative heuristics.

Coalescing heuristics

Briggs: coalesce nodes n_1 and n_2 to $n_{1\&2}$ iff:

$n_{1\&2}$ has less than K neighbors of significant degree (i.e. of a degree greater or equal to K),

George: coalesce nodes n_1 and n_2 to $n_{1\&2}$ iff all neighbors of n_1 either:

- already interfere with n_2, or
- are of insignificant degree.

Both heuristics are:

- safe: won't make a K-colorable graph uncolorable,
- conservative: might prevent a safe coalescing.

Heuristic #1: Briggs

Briggs: coalesce nodes n_1 and n_2 to $n_{1\&2}$ iff:

$n_{1\&2}$ has less than K neighbors of significant degree (i.e. of a degree ≥ K),

Rationale:

- during simplification, all the neighbors of $n_{1\&2}$ that are of insignificant degree will be simplified;
- once they are, $n_{1\&2}$ will have less than K neighbors and will therefore be simplifiable too.

Heuristic #2: George

George: coalesce nodes n_1 and n_2 to $n_{1\&2}$ iff all neighbors of n_1 either:

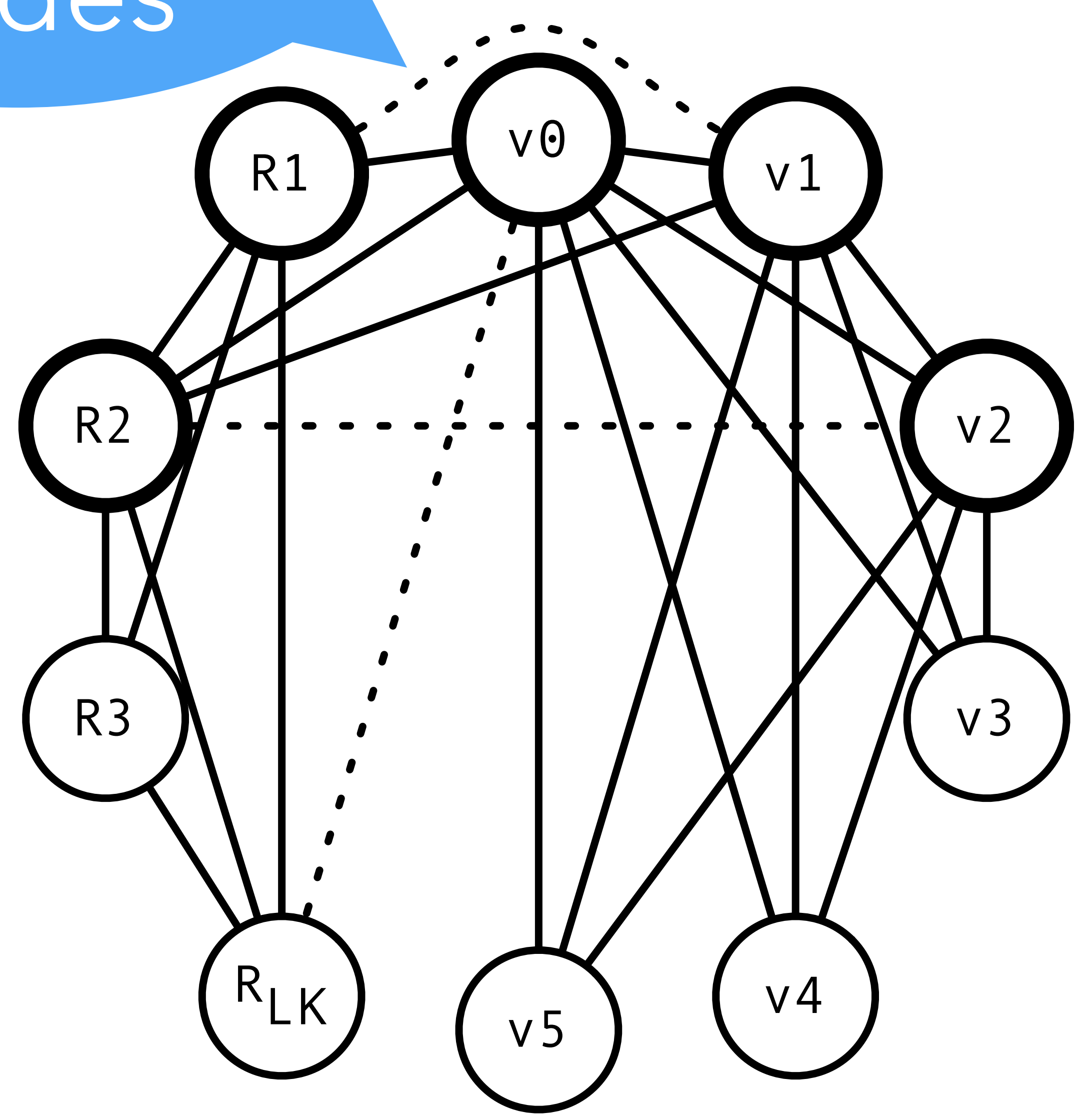
- already interfere with n_2, or
- are of insignificant degree.

Rationale:

- the neighbors of $n_{1\&2}$ will be:
  1. those of n_2, and
  2. the neighbors of n_1 of insignificant degree,
- the latter ones will all be simplified,
- once they are, the graph will be a sub-graph of the original one.

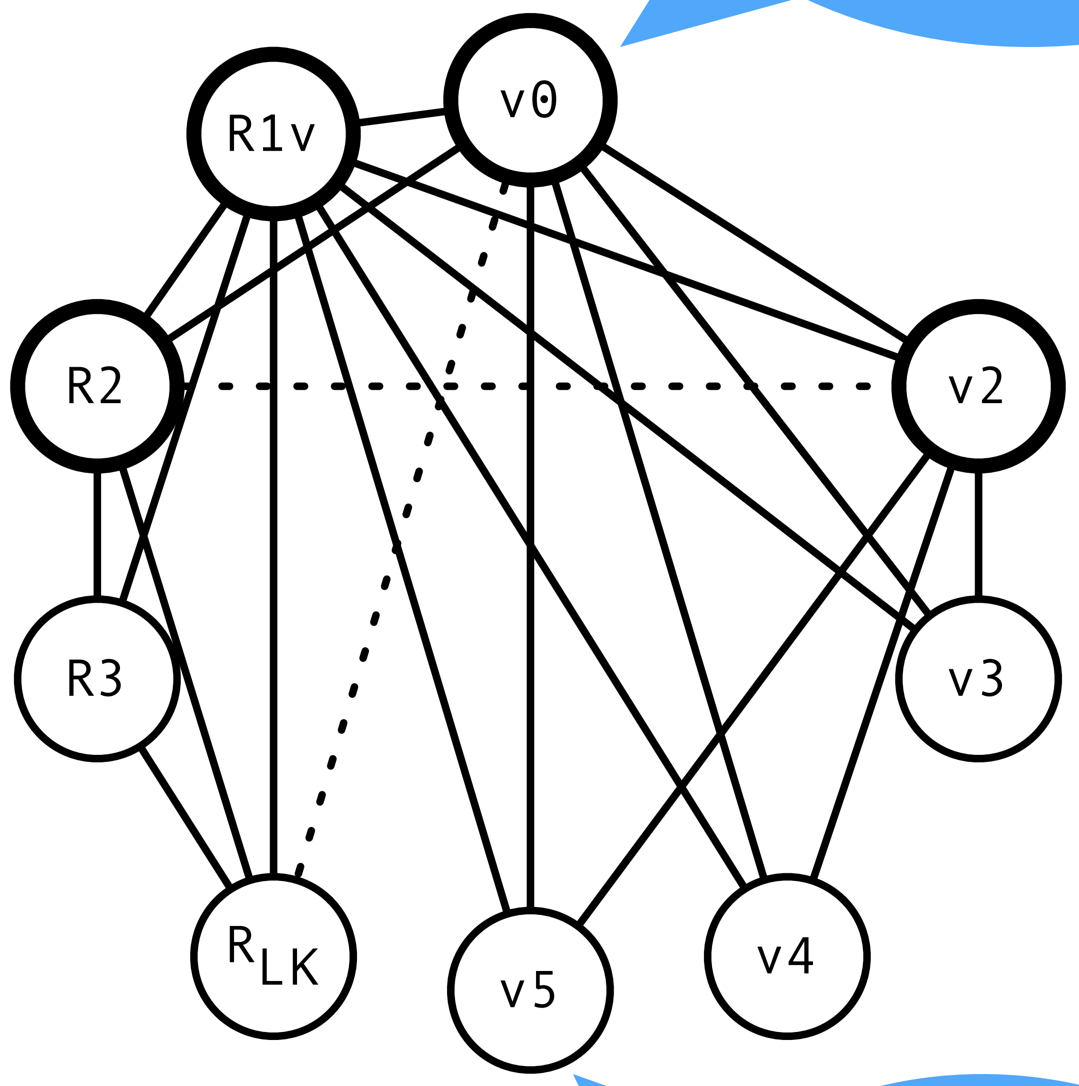
Coalescing example

non-interfering, move-related nodes



coalescing of R_1 and v_1 into R_{1v}

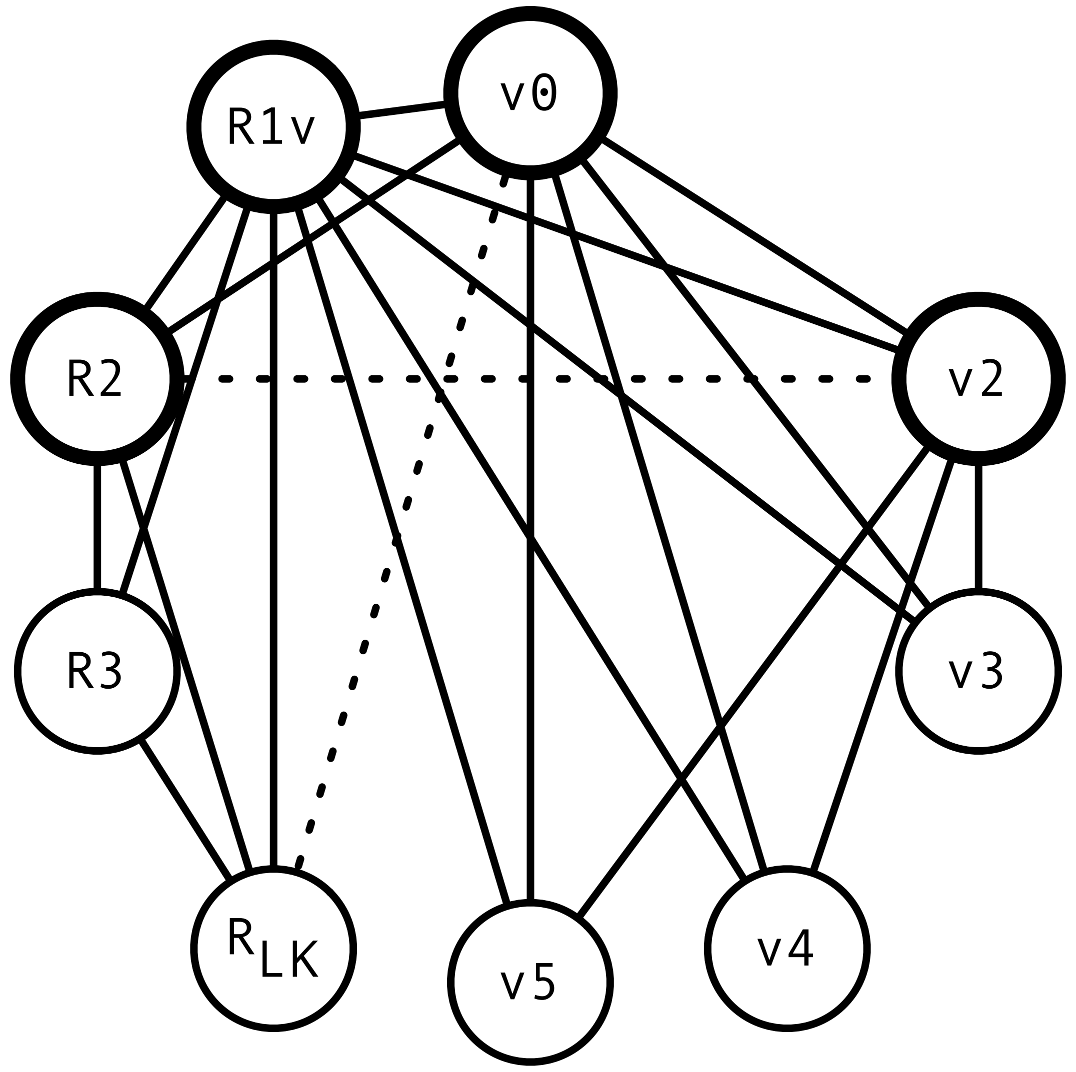
safe according to Briggs *and* George with $K = 4$



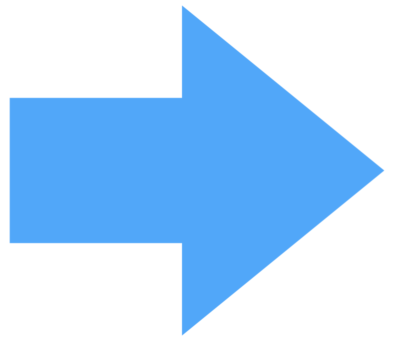
node of significant degree

node of insignificant degree

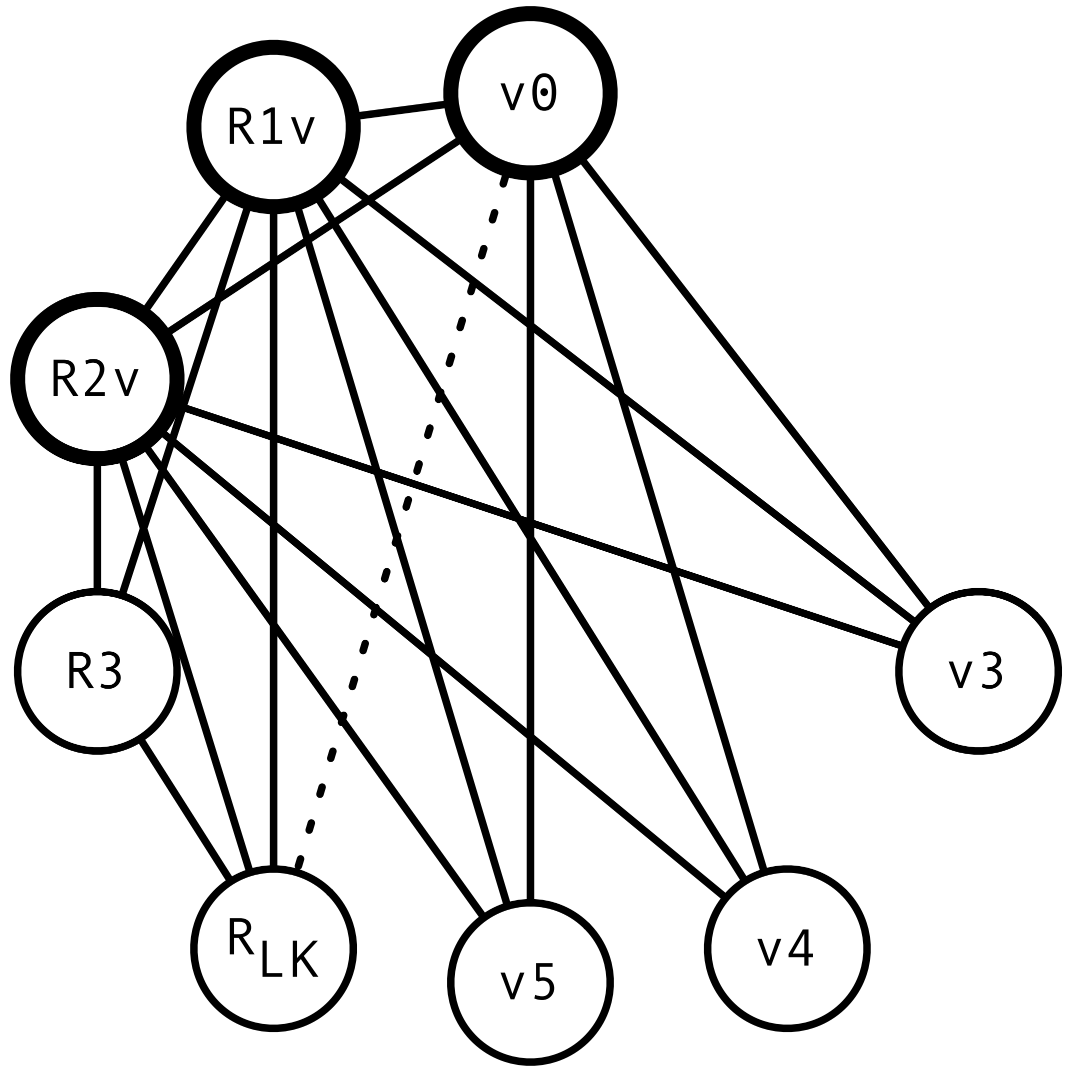
Coalescing example (2)



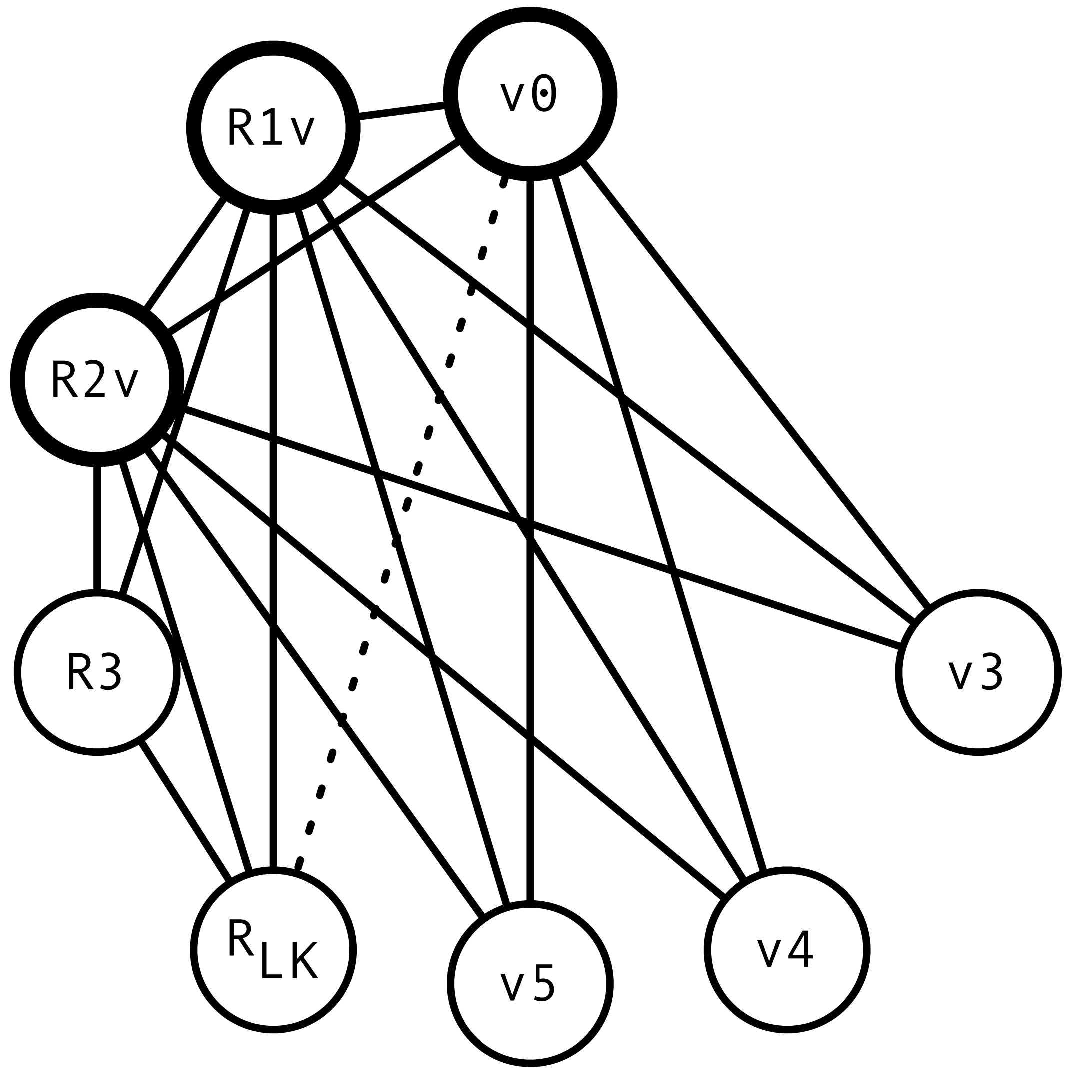
coalescing of R_2 and v_2 into R_{2v}



safe according to Briggs *and* George with K = 4

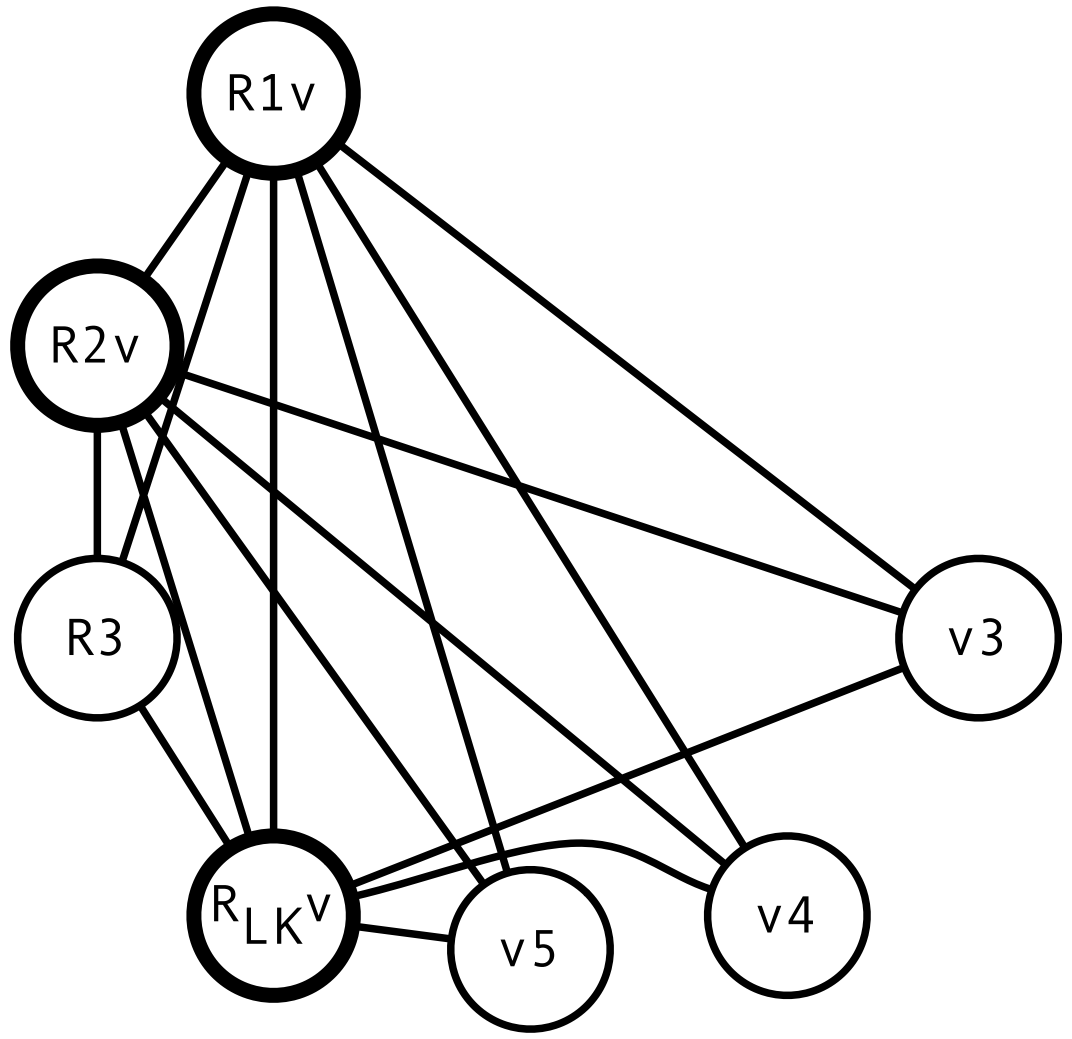


Coalescing example (3)

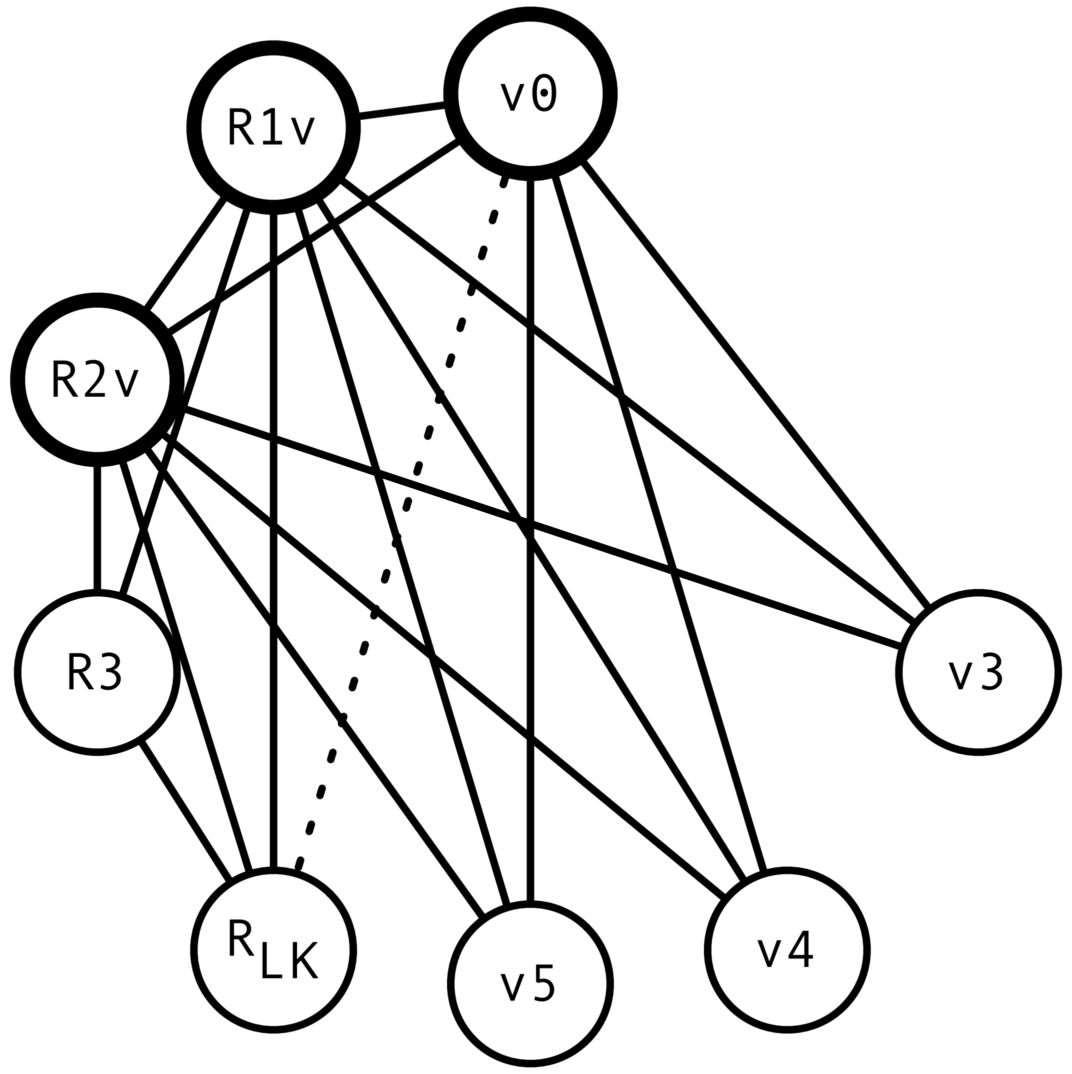


coalescing of R_{LK} and v_0 into R_{LKv}

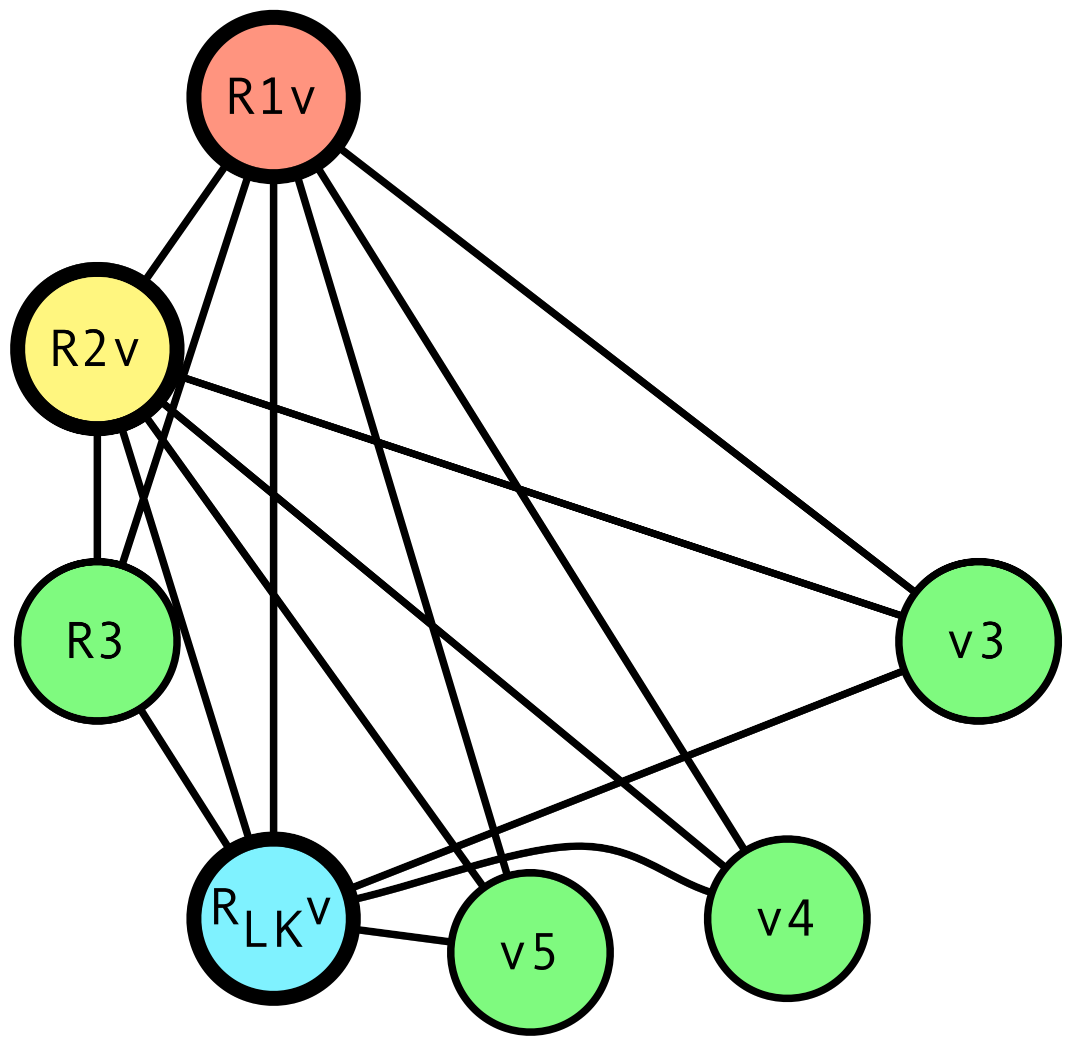
safe according to Briggs *and* George with $K = 4$



Coalescing example (3)



coalescing of R_{LK} and v_0 into R_{LKv}



safe according to Briggs *and* George with $K = 4$

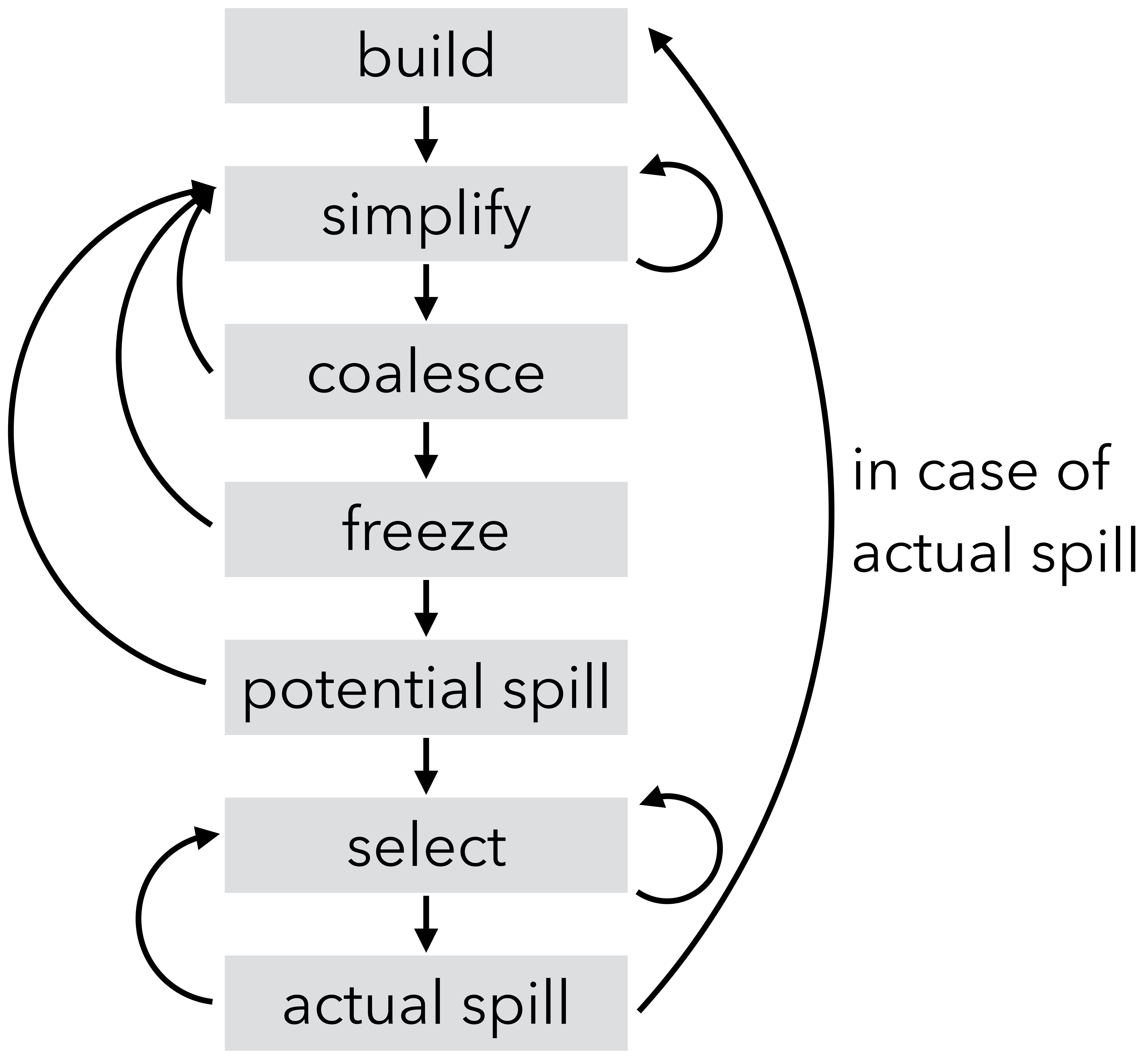
Putting it all together

Iterated register coalescing

Simplification and coalescing should be interleaved to get **iterated register coalescing**:

1. Interference graph nodes are partitioned in two classes: move-related or not.
2. Simplification is done on *not* move-related nodes (as move-related ones could be coalesced).
3. Conservative coalescing is performed.
4. When neither simplification nor coalescing can proceed further, some move-related nodes are **frozen** (marked as non-move-related).
5. The process is restarted at 2.

Iterated register coalescing



Assignment constraints

Assignment constraints

Current assumption: a virtual register can be assigned to any free physical register.

Not always true because of **assignment constraints** due to:

- registers classes (e.g. integer vs. floating-point registers),
- instructions with arguments or result in specific registers,
- calling conventions.

A realistic register allocator has to be able to satisfy these constraints.

Register classes

Most architectures have several register classes:

- integer vs floating-point,
- address vs data,
- etc.

To take them into account in a coloring-based allocator:

introduce artificial interferences between a node and all pre-colored nodes corresponding to registers to which it *cannot* be allocated.

Calling conventions

How to deal with the fact that calling conventions pass arguments in specific registers?

At function entry, copy arguments to new virtual regs:

```
fact:
    v₁ ← R₁       ; copy first argument to v₁
```

Before a call, load arguments in appropriate registers:

```
    R₁ ← v₂       ; load first argument from v₂
    CALL fact
```

Whenever possible, these instructions will be removed by coalescing.

Caller/callee-saved registers

Calling conventions distinguish two kinds of registers:

- **caller-saved**: saved by the caller before a call and restored after it,
- **callee-saved**: saved by the callee at function entry and restored before function exit.

Ideally:

- virtual registers having to survive at least one call should be assigned to callee-saved registers,
- other virtual registers should be assigned to caller-saved registers.

How can this be obtained in a coloring-based allocator?

Caller/callee-saved registers

Caller-saved registers do not survive a function call.

To model this:

 Add interference edges between all virtual registers live across at least one call and (physical) caller-saved registers.

Consequence:

 Virtual registers live across at least one call won't be assigned to caller-saved registers.

Therefore:

 They will either be allocated to callee-saved registers, or spilled!

Saving callee-saved registers

Callee-saved registers must be preserved by all functions, so:

- copy them to fresh temporary registers at function entry,
- restore them before exit.

Saving callee-saved registers

For example, if R_8 is callee-saved:

```
entry:
   v₁ ← R₈   ; save callee-saved R₈ in v₁
   …         ; function body
   R₈ ← v₁   ; restore callee-saved R₈
   goto R_LK
```

If register pressure is low:

- R_8 and v_1 will be coalesced, and
- the two move instructions will be removed.

If register pressure is high:

- v_1 will be spilled, making R_8 available in the function (e.g. to store a virtual register live across a call).

Technique #2: linear scan

Linear scan

The basic linear scan technique is very simple:

- the program is linearized – i.e. represented as a linear sequence of instructions, not as a graph,
- a unique live range is computed for every variable, going from the first to the last instruction during which it is live,
- registers are allocated by iterating over the intervals sorted by increasing starting point: each time an interval starts, the next free register is allocated to it, and each time an interval ends, its register is freed,
- if no register is available, the active range ending last is chosen to have its variable spilled.

Linear scan example

Linearized version of GCD computation:

Program

```
1   gcd:   v0 ← RLK
2          v1 ← R1
3          v2 ← R2
4   loop:  v3 ← done
5          if v2=0 goto v3
6          v4 ← v2
7          v2 ← v1 % v2
8          v1 ← v4
9          v5 ← loop
10         goto v5
11  done:  R1 ← v1
12         goto v0
```

Live ranges

v_0: $[1^+, 12^-]$

v_1: $[2^+, 11^-]$

v_2: $[3^+, 10^+]$

v_3: $[4^+, 5^-]$

v_4: $[6^+, 8^-]$

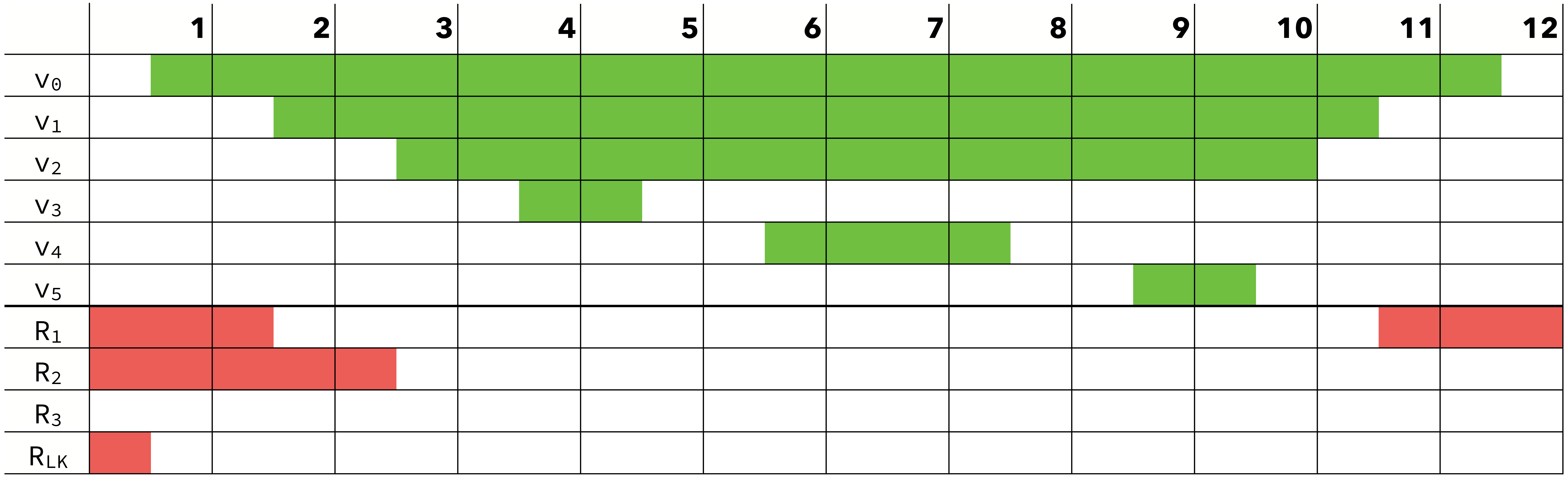
v_5: $[9^+, 10^-]$

Notation:

i^+ entry of instr. i

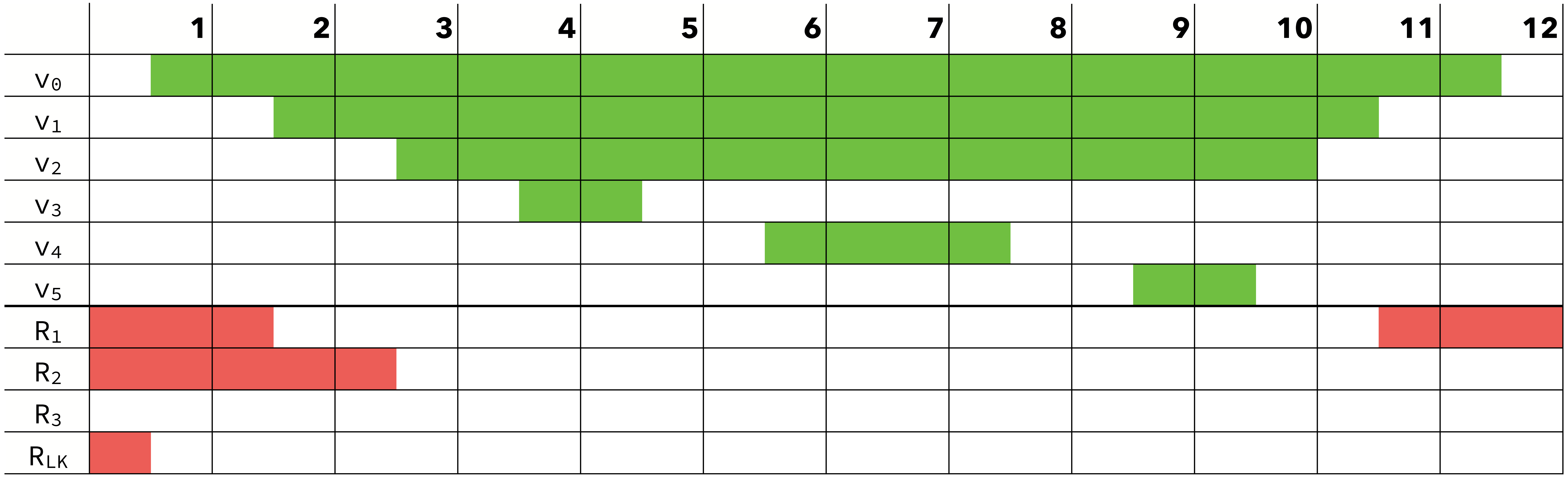
i^- exit of instr. i

Linear scan example (4 r.)



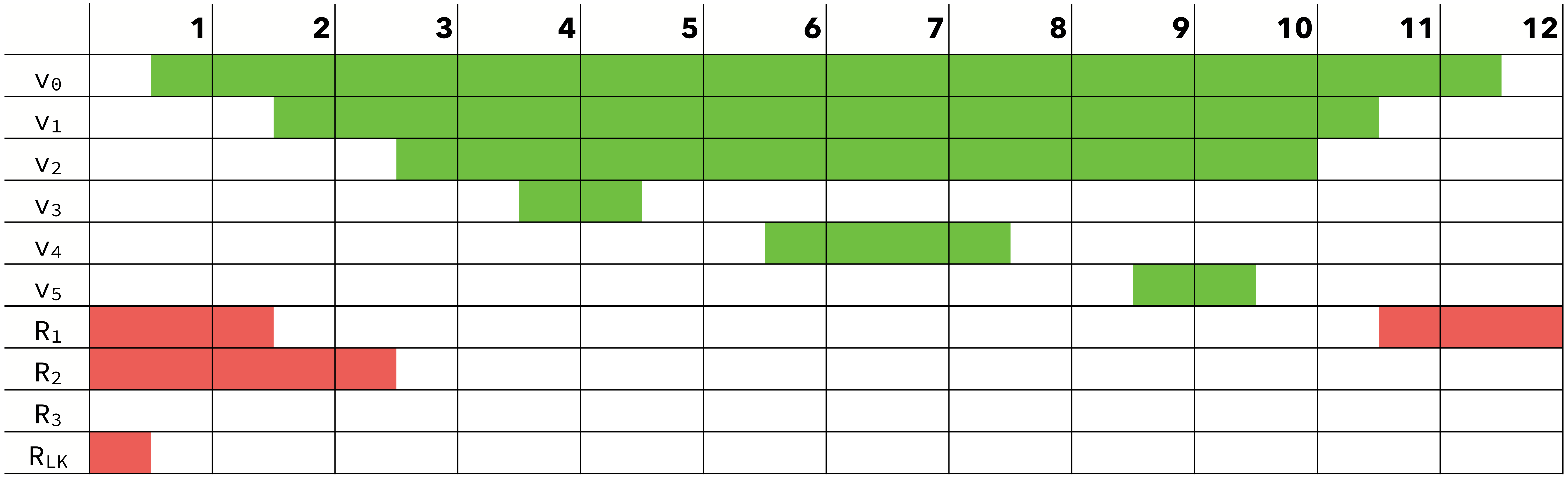
time	active intervals	allocation

Linear scan example (4 r.)



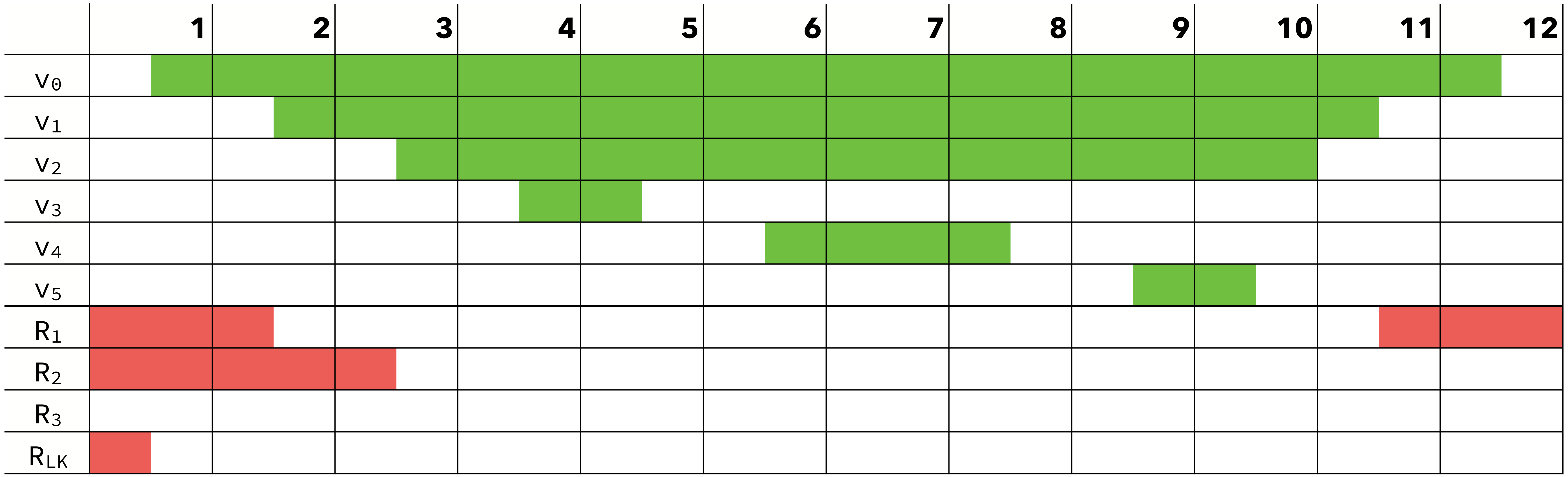
time	active intervals	allocation
1^+	$[1^+, 12^-]$	$v_0 \to R_3$

Linear scan example (4 r.)



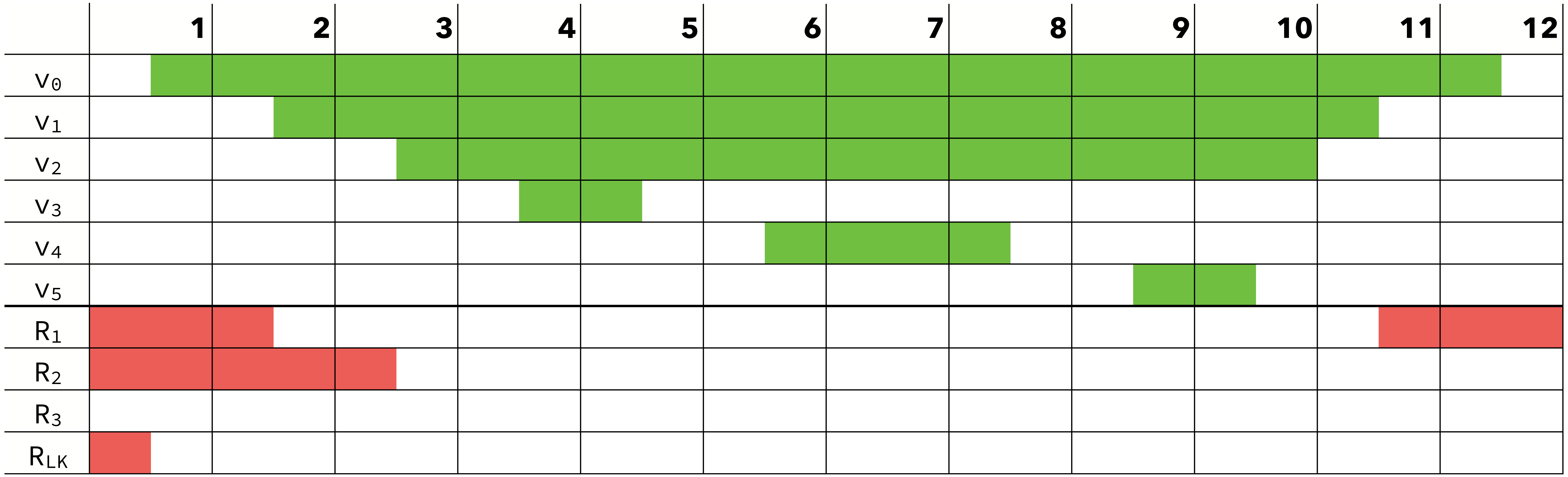
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \rightarrow R_3$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \rightarrow R_3$, $v_1 \rightarrow R_1$

Linear scan example (4 r.)



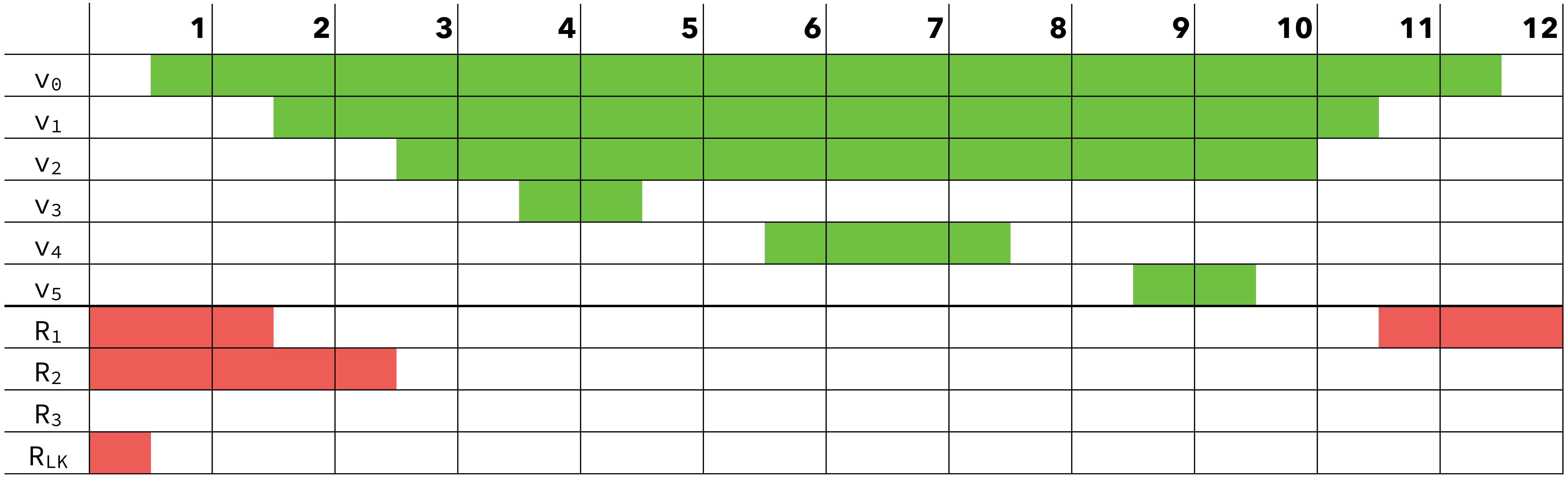
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \to R_3$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$
3^+	$[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$, $v_2 \to R_2$

Linear scan example (4 r.)



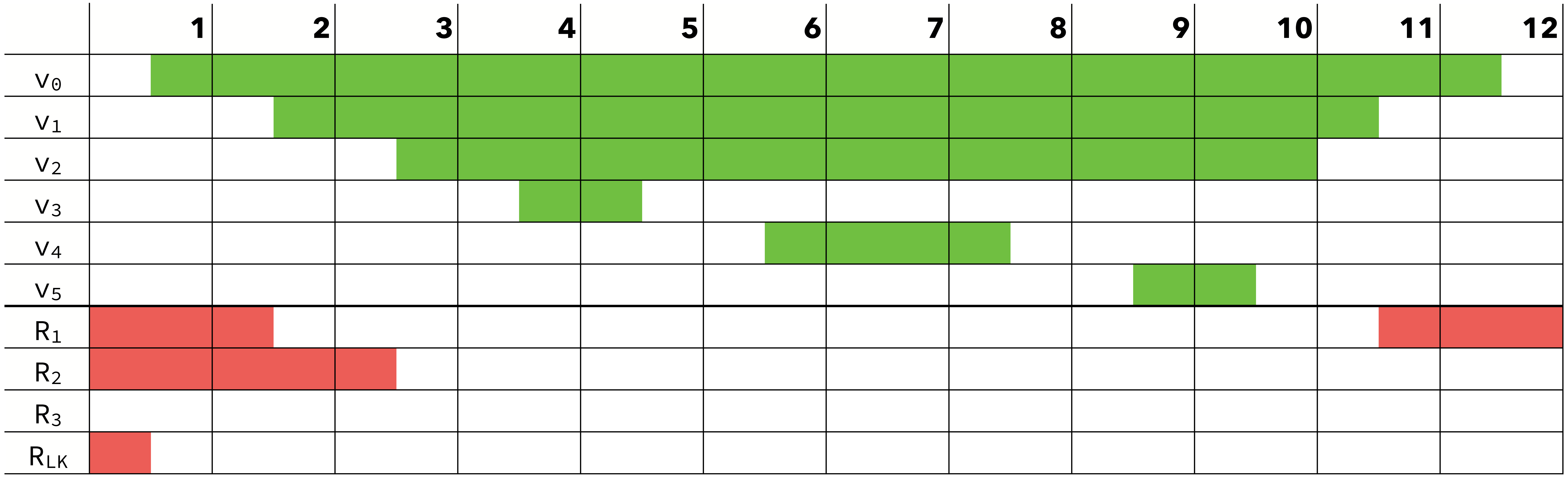
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \rightarrow R_3$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \rightarrow R_3, v_1 \rightarrow R_1$
3^+	$[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \rightarrow R_3, v_1 \rightarrow R_1, v_2 \rightarrow R_2$
4^+	$[4^+,5^-],[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \rightarrow R_3, v_1 \rightarrow R_1, v_2 \rightarrow R_2, v_3 \rightarrow R_{LK}$

Linear scan example (4 r.)



time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \to R_3$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3, v_1 \to R_1$
3^+	$[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3, v_1 \to R_1, v_2 \to R_2$
4^+	$[4^+,5^-],[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3, v_1 \to R_1, v_2 \to R_2, v_3 \to R_{LK}$
6^+	$[6^+,8^-],[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3, v_1 \to R_1, v_2 \to R_2, v_4 \to R_{LK}$

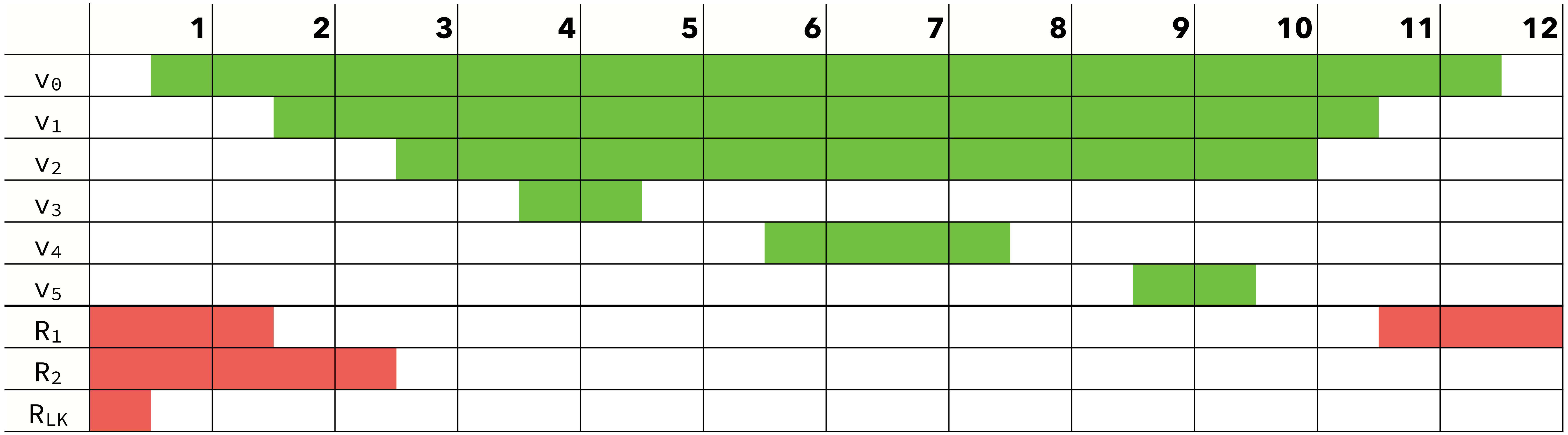
Linear scan example (4 r.)



time active intervals	allocation
1^+ $[1^+,12^-]$	$v_0 \to R_3$
2^+ $[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$
3^+ $[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$, $v_2 \to R_2$
4^+ $[4^+,5^-],[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$, $v_2 \to R_2$, $v_3 \to R_{LK}$
6^+ $[6^+,8^-],[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$, $v_2 \to R_2$, $v_4 \to R_{LK}$
9^+ $[9^+,10^-],[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_3$, $v_1 \to R_1$, $v_2 \to R_2$, $v_5 \to R_{LK}$

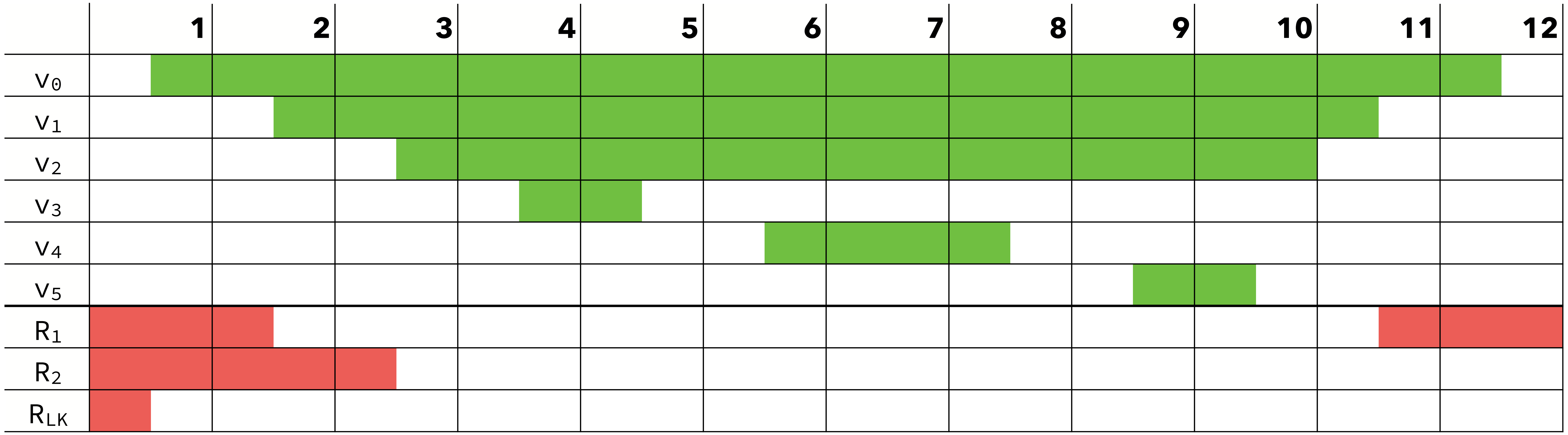
Result: no spilling

Linear scan example (3 r.)



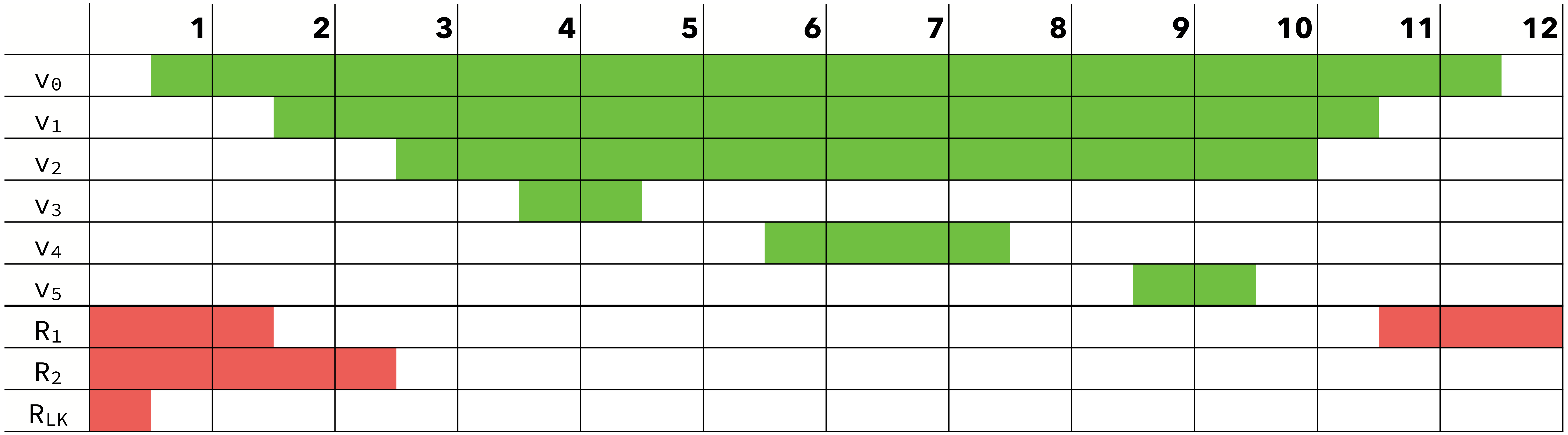
time	active intervals	allocation

Linear scan example (3 r.)



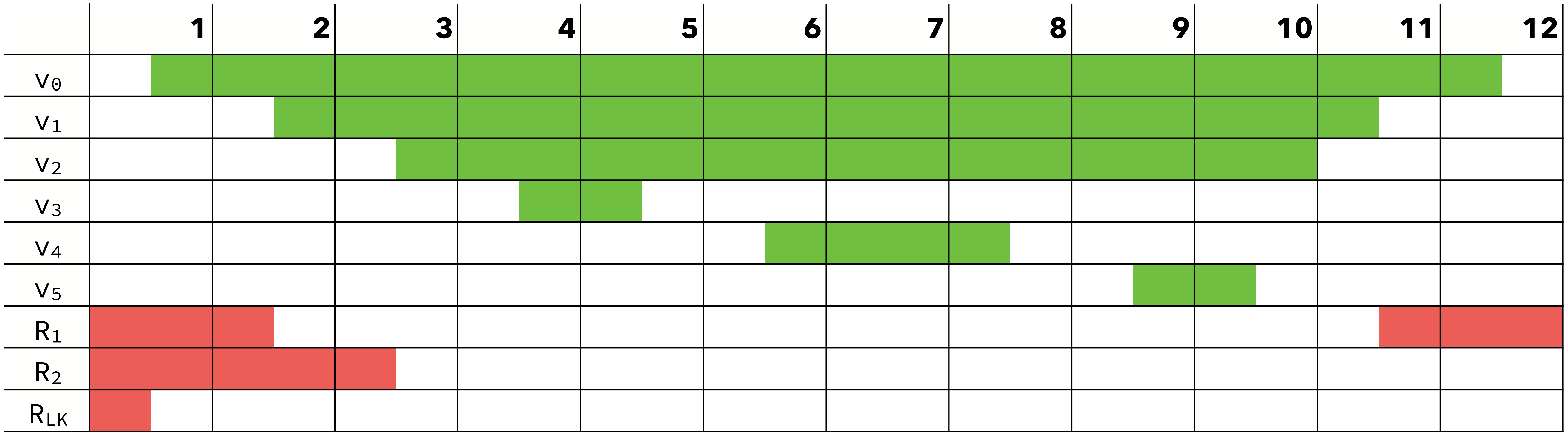
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \rightarrow R_{LK}$

Linear scan example (3 r.)



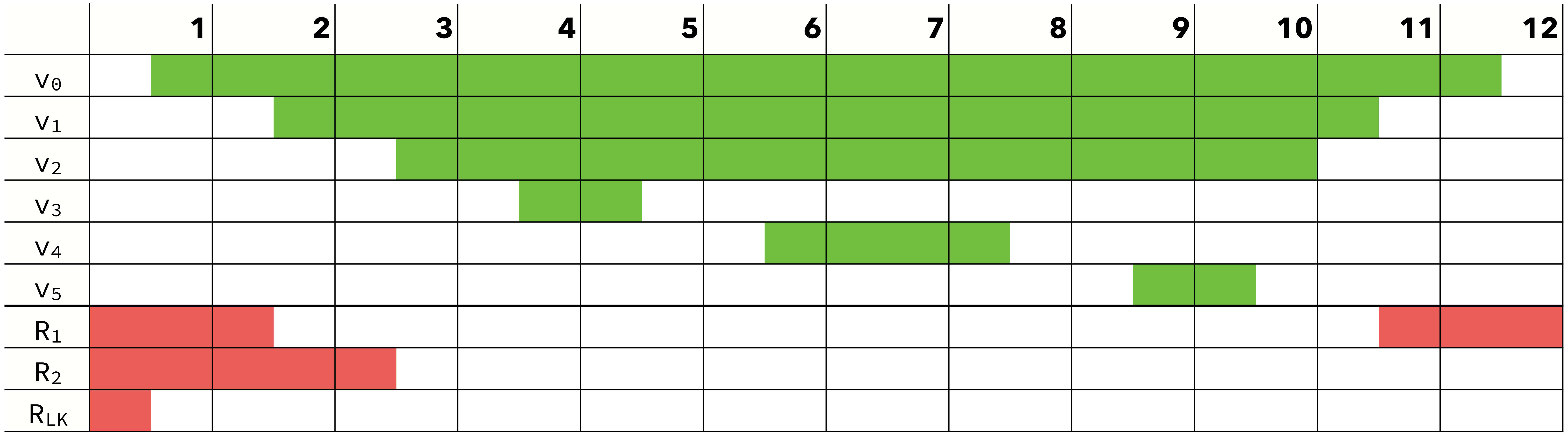
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \to R_{LK}$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}$, $v_1 \to R_1$

Linear scan example (3 r.)



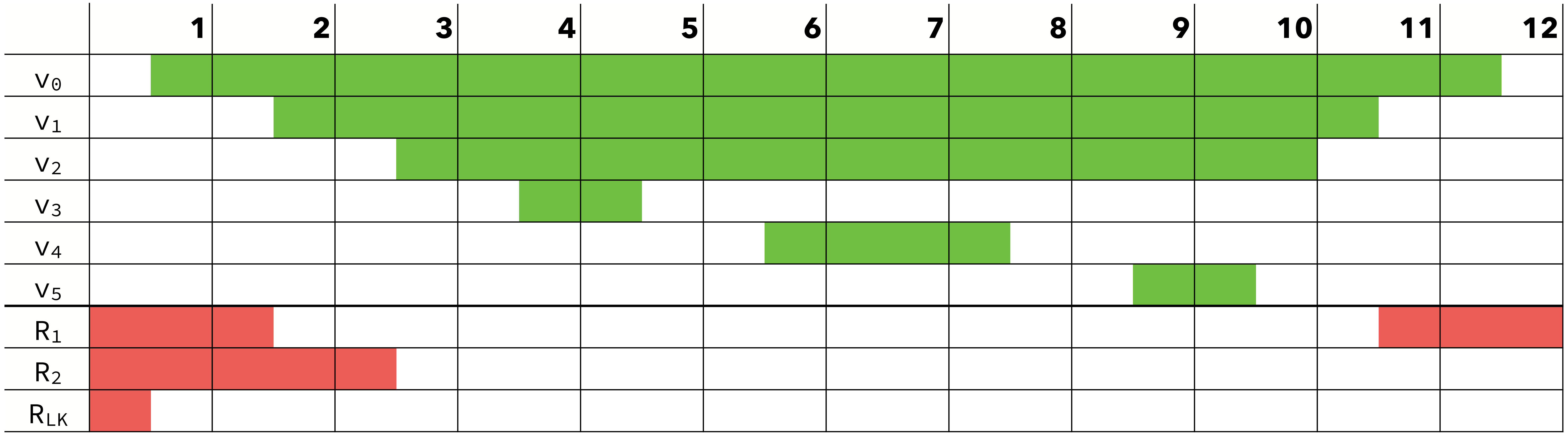
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \to R_{LK}$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}, v_1 \to R_1$
3^+	$[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}, v_1 \to R_1, v_2 \to R_2$

Linear scan example (3 r.)



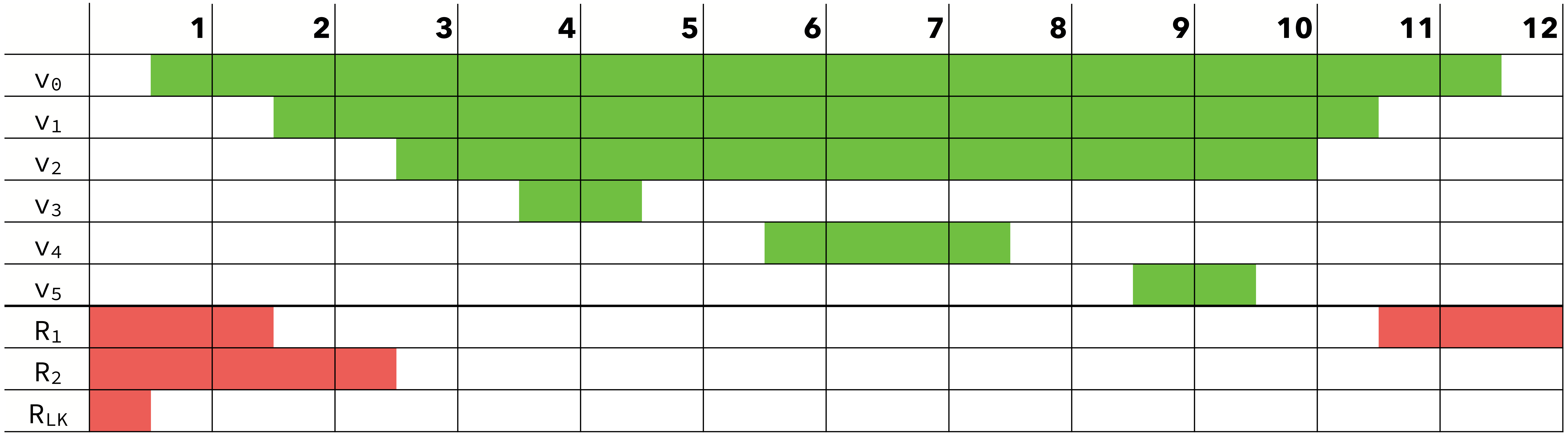
time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \to R_{LK}$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}$, $v_1 \to R_1$
3^+	$[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}$, $v_1 \to R_1$, $v_2 \to R_2$
4^+	$[4^+,5^-],[3^+,10^+],[2^+,11^-]$	$v_0 \to S$, $v_1 \to R_1$, $v_2 \to R_2$, $v_3 \to R_{LK}$

Linear scan example (3 r.)



time	active intervals	allocation
1^+	$[1^+,12^-]$	$v_0 \to R_{LK}$
2^+	$[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}, v_1 \to R_1$
3^+	$[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}, v_1 \to R_1, v_2 \to R_2$
4^+	$[4^+,5^-],[3^+,10^+],[2^+,11^-]$	$v_0 \to S, v_1 \to R_1, v_2 \to R_2, v_3 \to R_{LK}$
6^+	$[6^+,8^-],[3^+,10^+],[2^+,11^-]$	$v_0 \to S, v_1 \to R_1, v_2 \to R_2, v_4 \to R_{LK}$

Linear scan example (3 r.)



time active intervals	allocation
1^+ $[1^+,12^-]$	$v_0 \to R_{LK}$
2^+ $[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}$, $v_1 \to R_1$
3^+ $[3^+,10^+],[2^+,11^-],[1^+,12^-]$	$v_0 \to R_{LK}$, $v_1 \to R_1$, $v_2 \to R_2$
4^+ $[4^+,5^-],[3^+,10^+],[2^+,11^-]$	$v_0 \to S$, $v_1 \to R_1$, $v_2 \to R_2$, $v_3 \to R_{LK}$
6^+ $[6^+,8^-],[3^+,10^+],[2^+,11^-]$	$v_0 \to S$, $v_1 \to R_1$, $v_2 \to R_2$, $v_4 \to R_{LK}$
9^+ $[9^+,10^-],[3^+,10^+],[2^+,11^-]$	$v_0 \to S$, $v_1 \to R_1$, $v_2 \to R_2$, $v_5 \to R_{LK}$

Result: v_0 is spilled *during its whole life time*!

Linear scan improvements

The basic linear scan algorithm is very simple but still produces reasonably good code. It can be – and has been – improved in many ways:

- the liveness information about virtual registers can be described using a sequence of disjoint intervals instead of a single one,
- virtual registers can be spilled for only a part of their whole life time,
- more sophisticated heuristics can be used to select the virtual register to spill,
- etc.